

The boundary rigidity of lattices in products of trees

Annette Karrer (Technion - Israel Institute of Technology)

joint work with

Kasia Jankiewicz, Kim Ruane and Bakul Sathaye

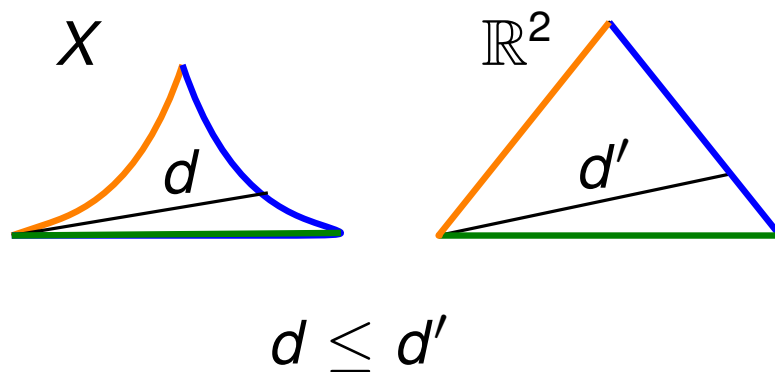
Outline

Goal: Show boundary rigidity of lattices in products of trees

- CAT(0) spaces and their boundaries
- Lattices in products of trees
- Theorem with proof idea

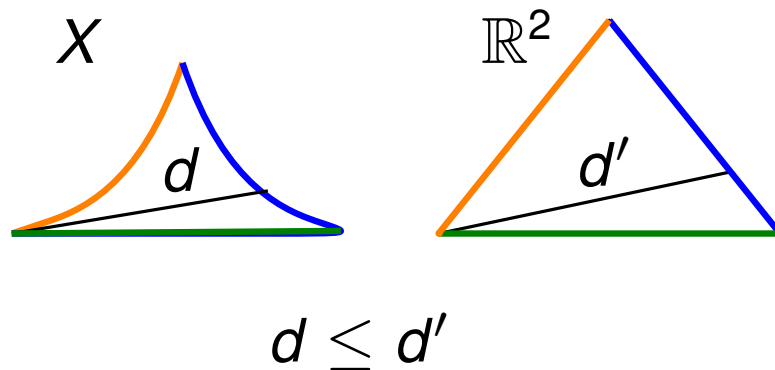
CAT(0) spaces

All spaces in this talk are CAT(0) (if not said otherwise)



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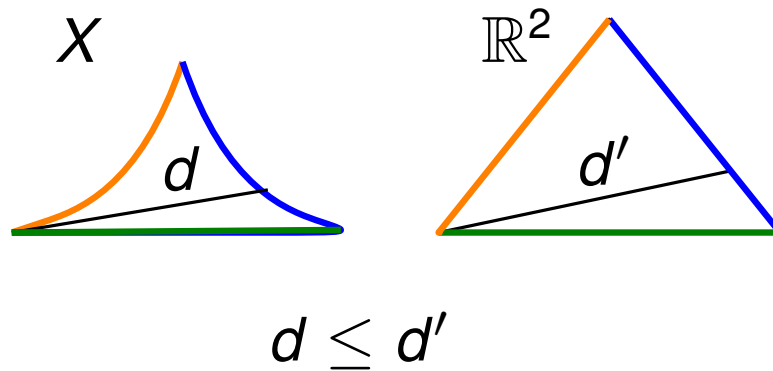


Examples:

■ \mathbb{R}^2 , \mathbb{H}^2 , trees,

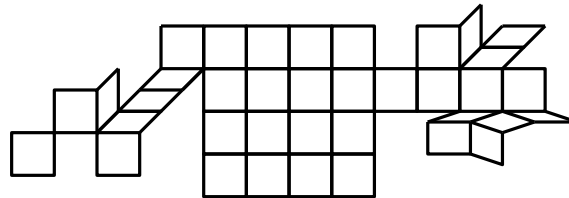
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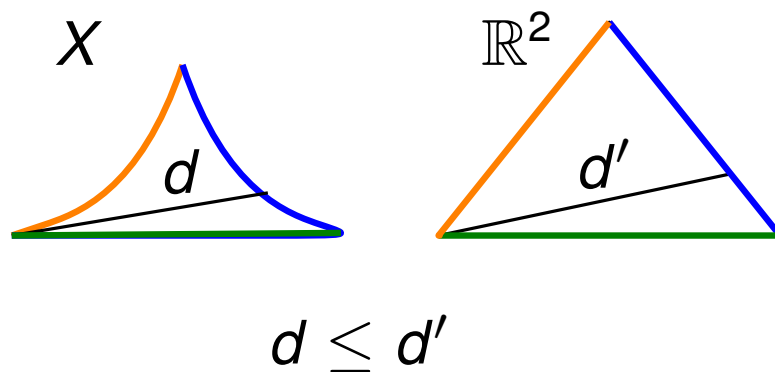
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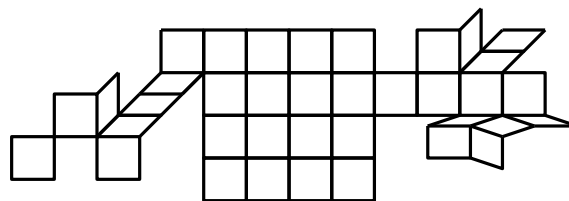
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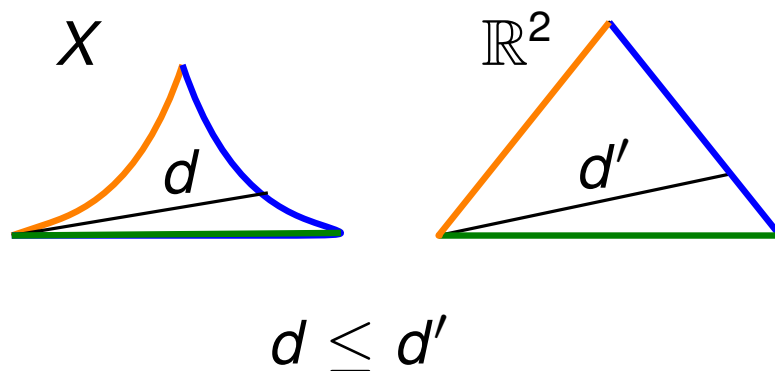
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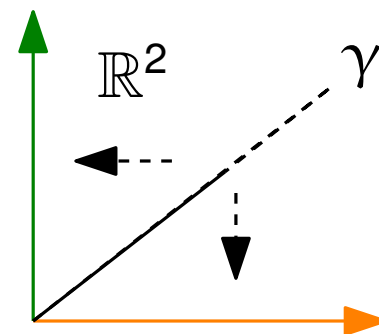
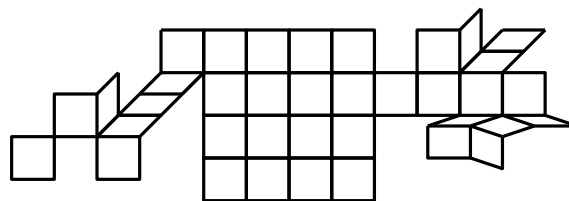
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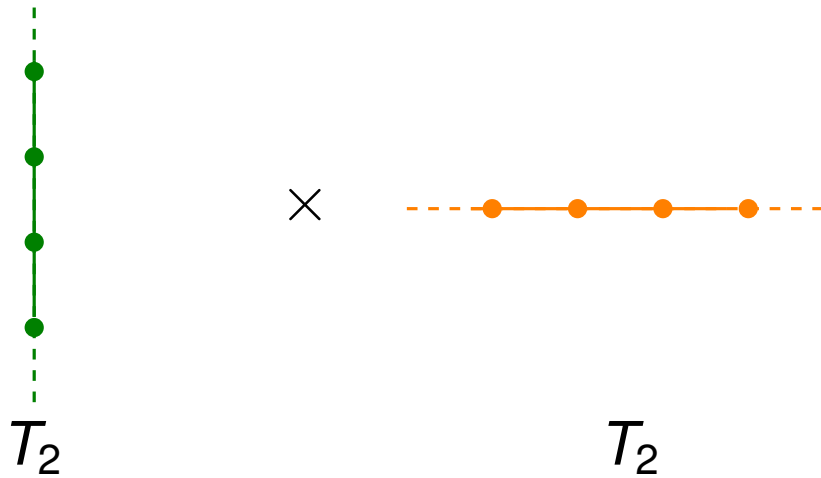
$\text{daim}(X_1) = \text{diam}(X_2) = \infty \Rightarrow$ each geodesic ray γ lies in a flat!

CAT(0) spaces

Example: T_n , T_m regular trees

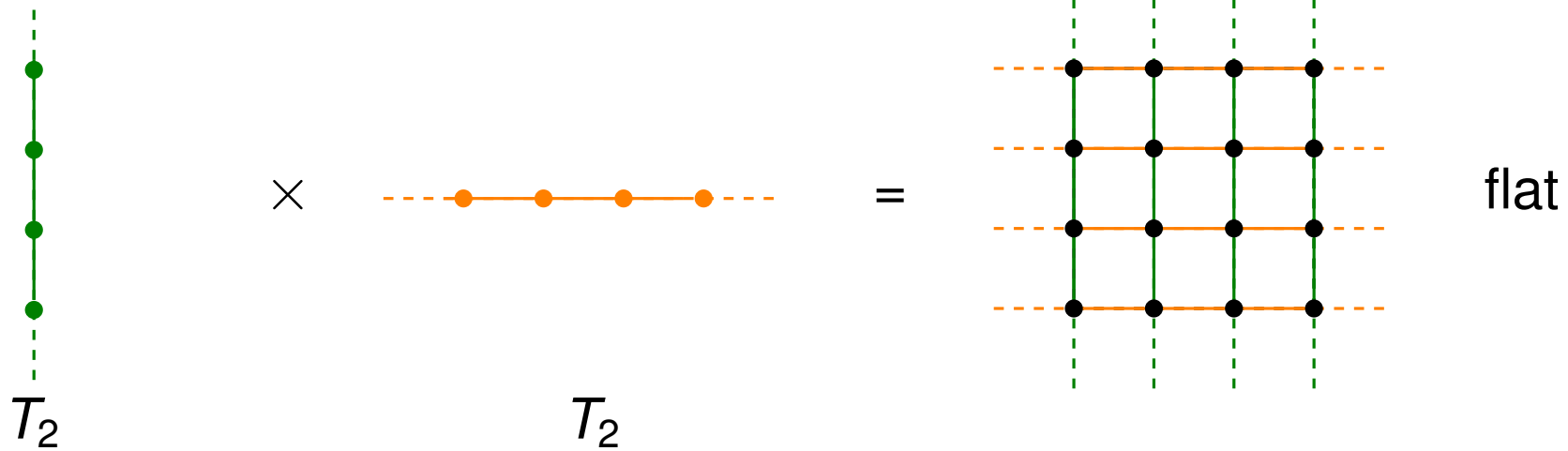
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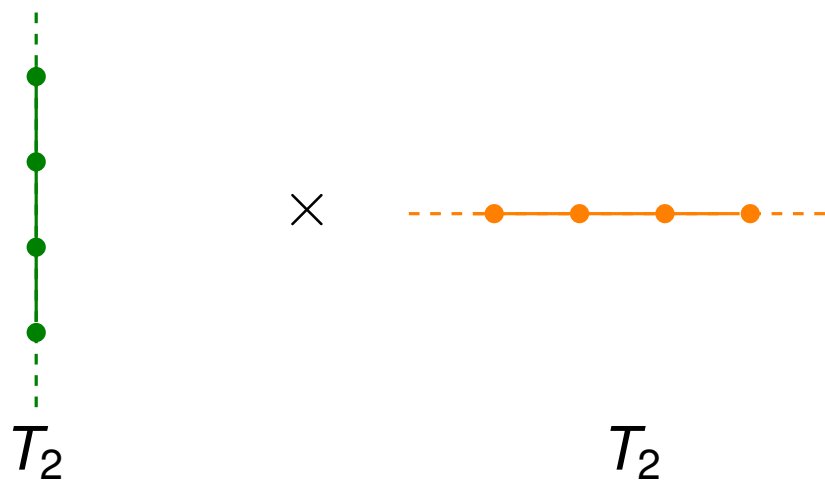
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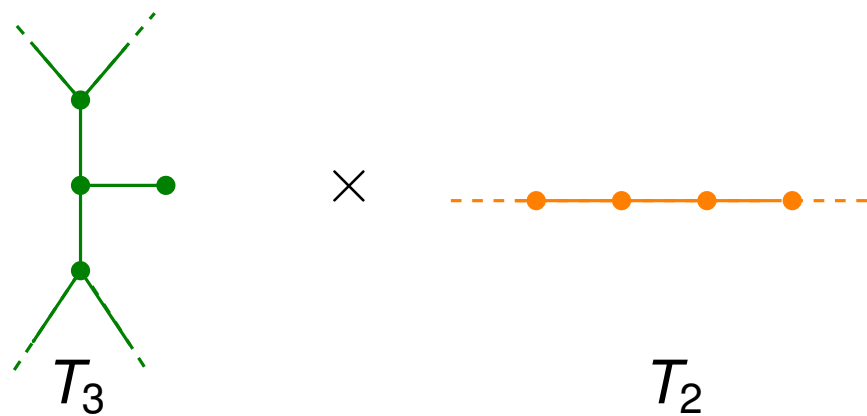


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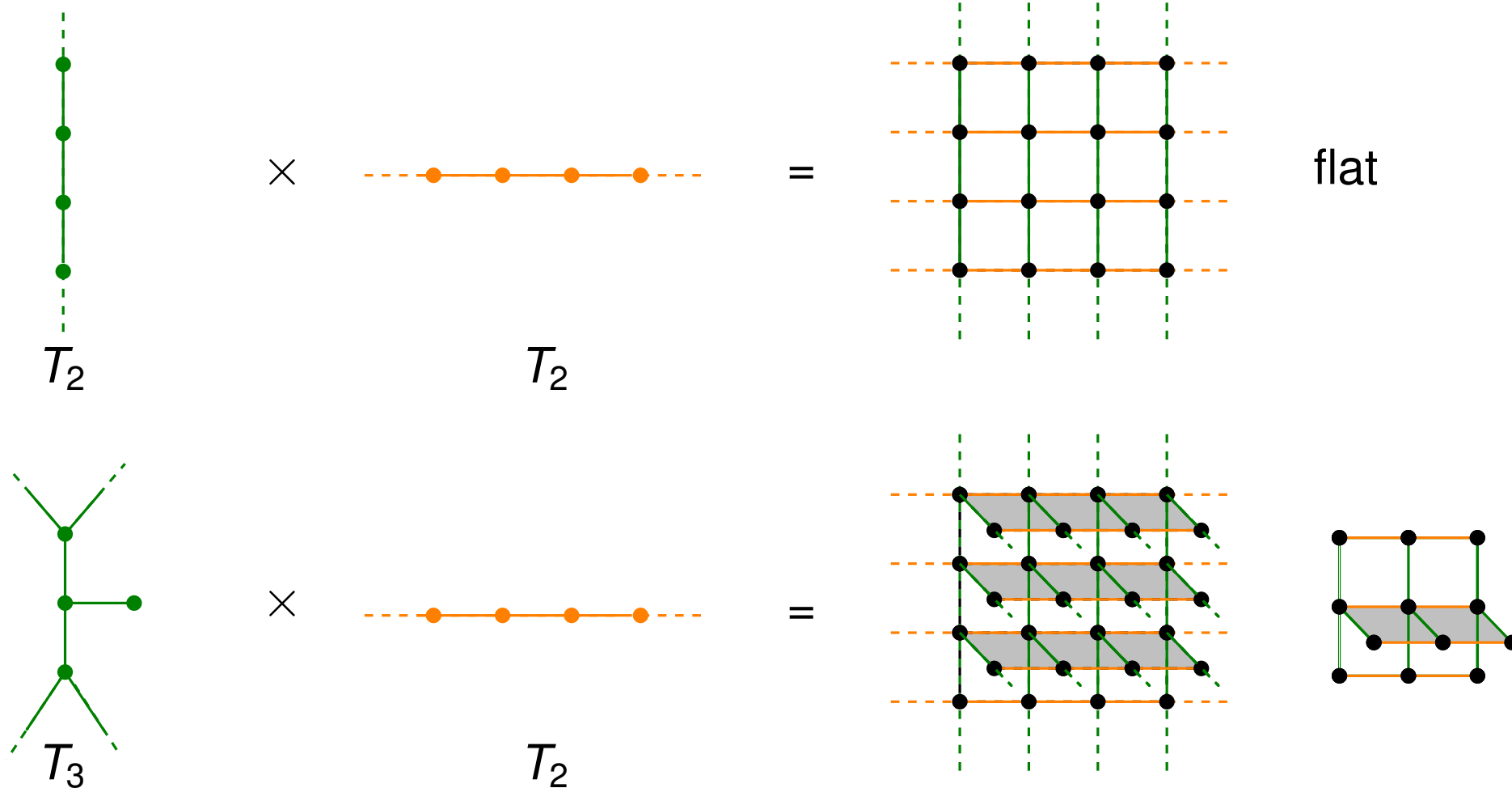


flat



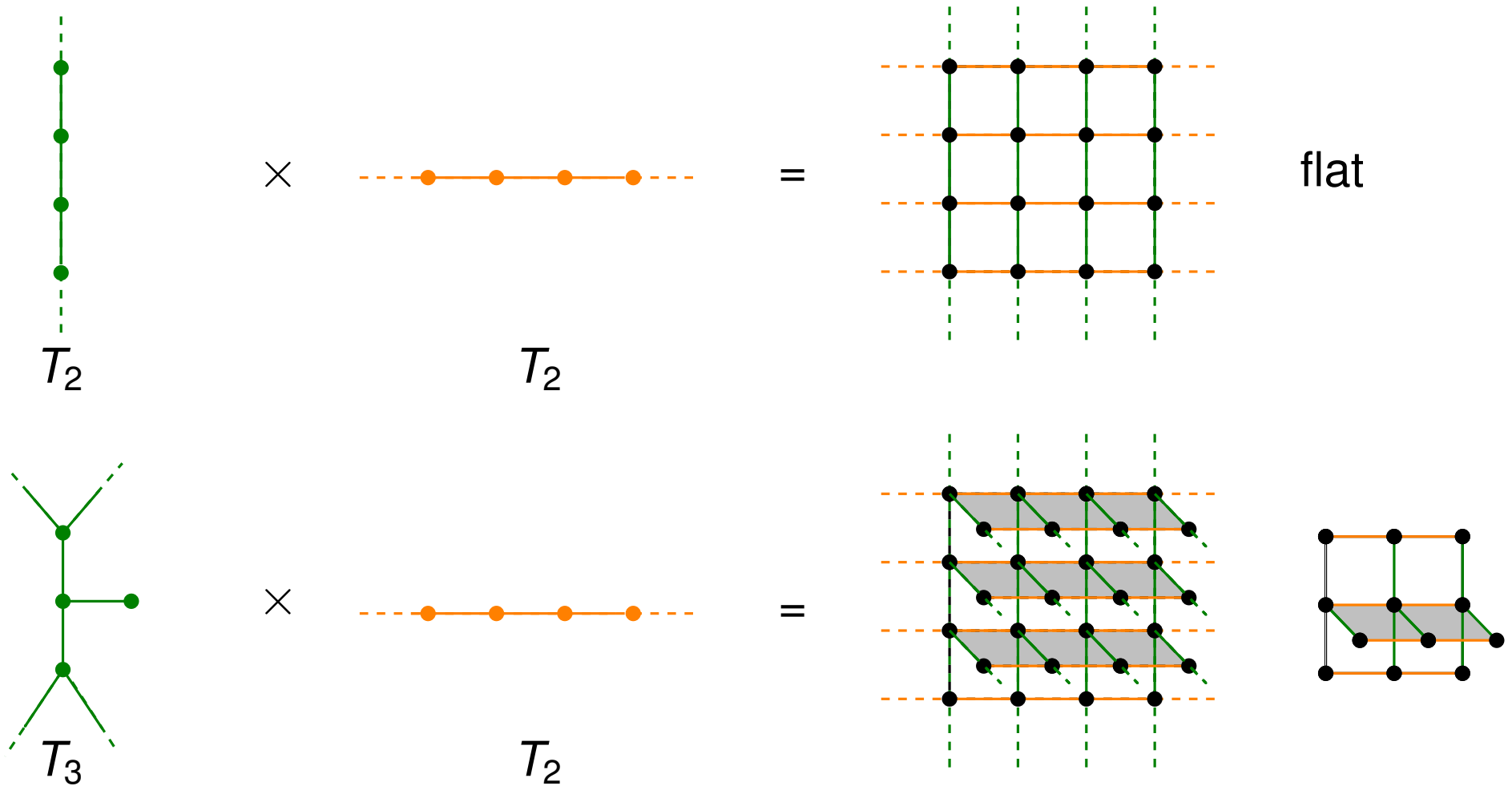
CAT(0) spaces

Example: T_n, T_m regular trees



CAT(0) spaces

Example: T_n, T_m regular trees $\Rightarrow T_n \times T_m$ CAT(0) square complex



Visual boundary

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X complete CAT(0) space

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$$\partial X := \{ \gamma \mid \gamma: [0, \infty) \rightarrow X \text{ geodesic ray} \} / \sim$$

$\gamma_1 \sim \gamma_2$ iff γ_1, γ_2 are close, i.e. $\exists C > 0$ s.t. $d(\gamma_1(t), \gamma_2(t)) \leq C \forall t \geq 0$.

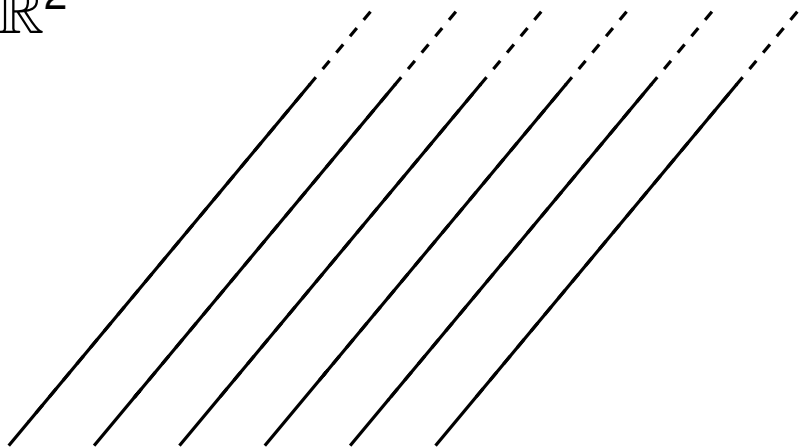
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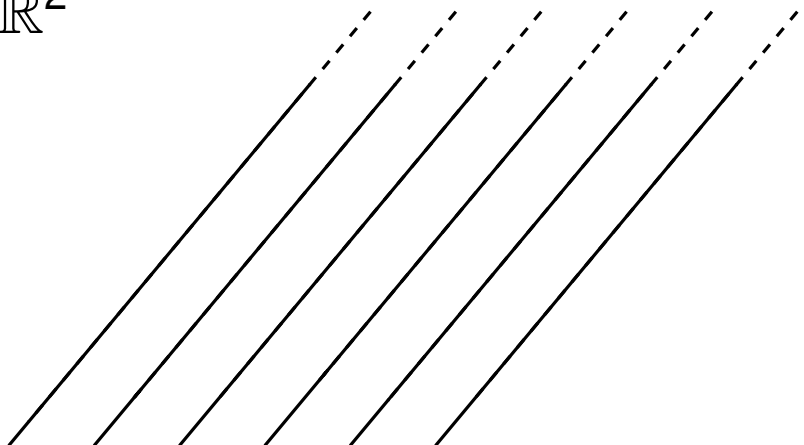
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Fact: $\forall p \in X, \bar{\gamma} \in \partial X \exists$ a geodesic ray $\gamma_p \in \bar{\gamma}$ that starts at p .

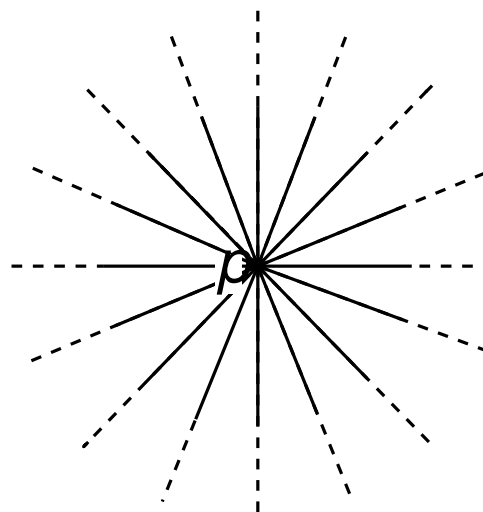
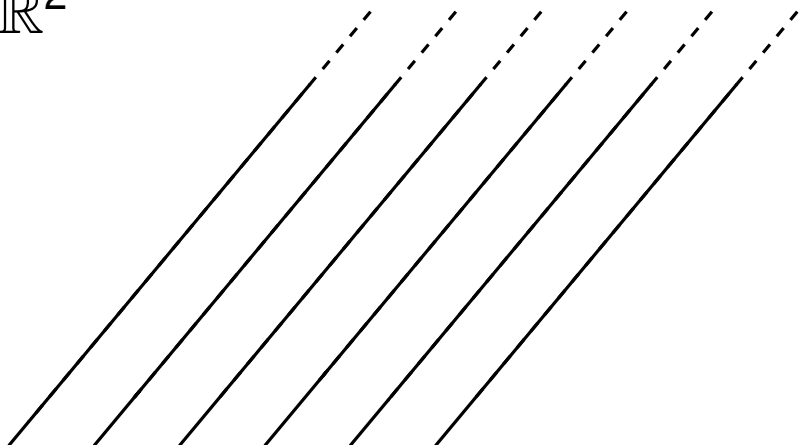
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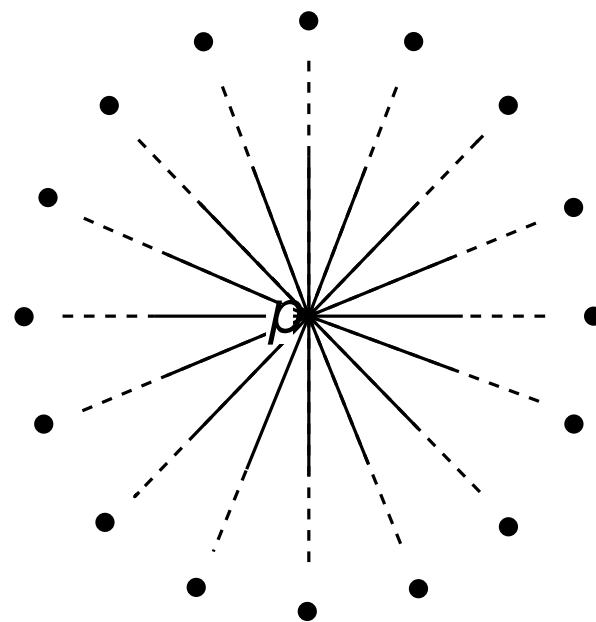
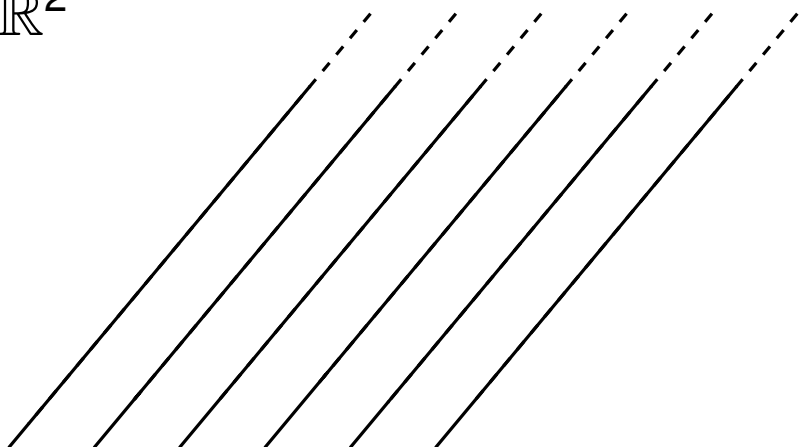
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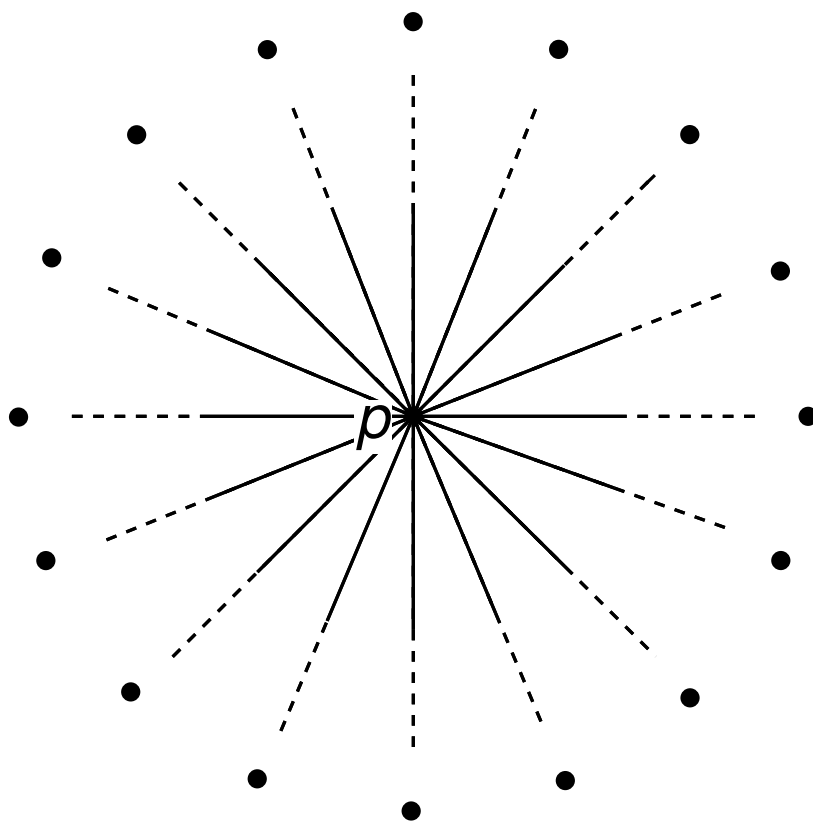
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Cone topology of the visual boundary

X complete CAT(0) space, $p \in X$

$$\partial X_p := \{\gamma \mid \gamma: [0, \infty) \rightarrow X \text{ geodesic ray, } \gamma(0) = p\}$$

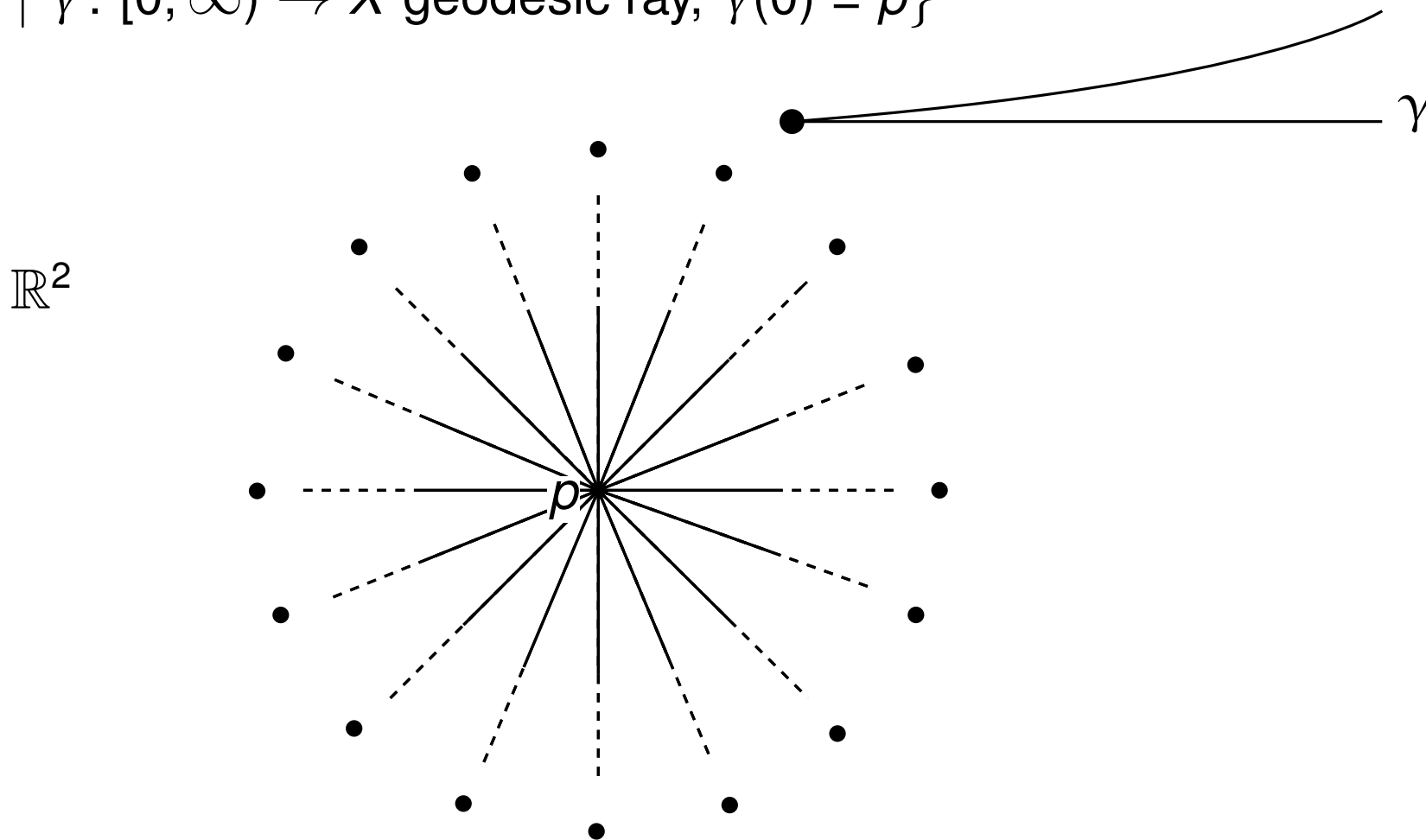
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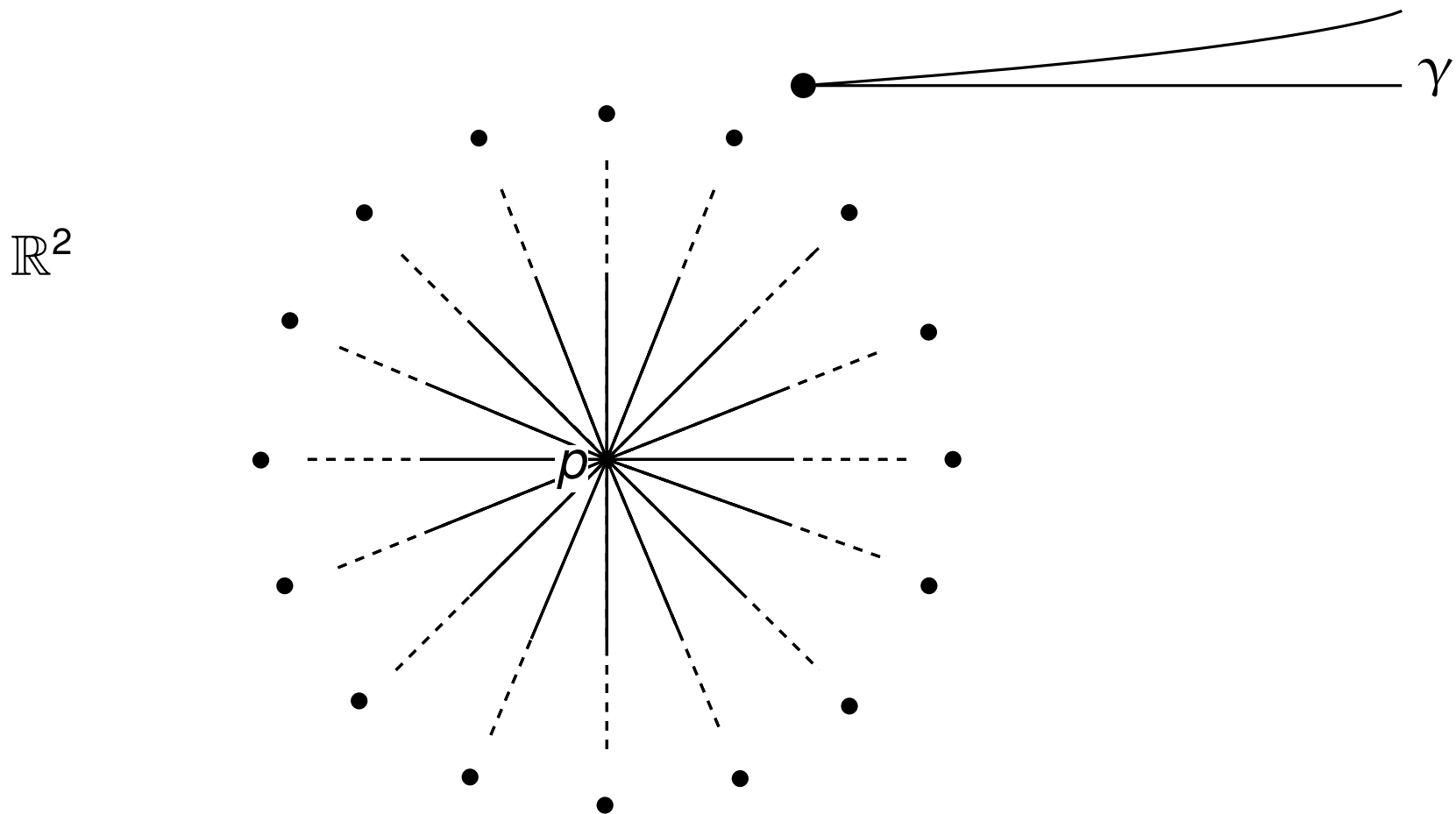
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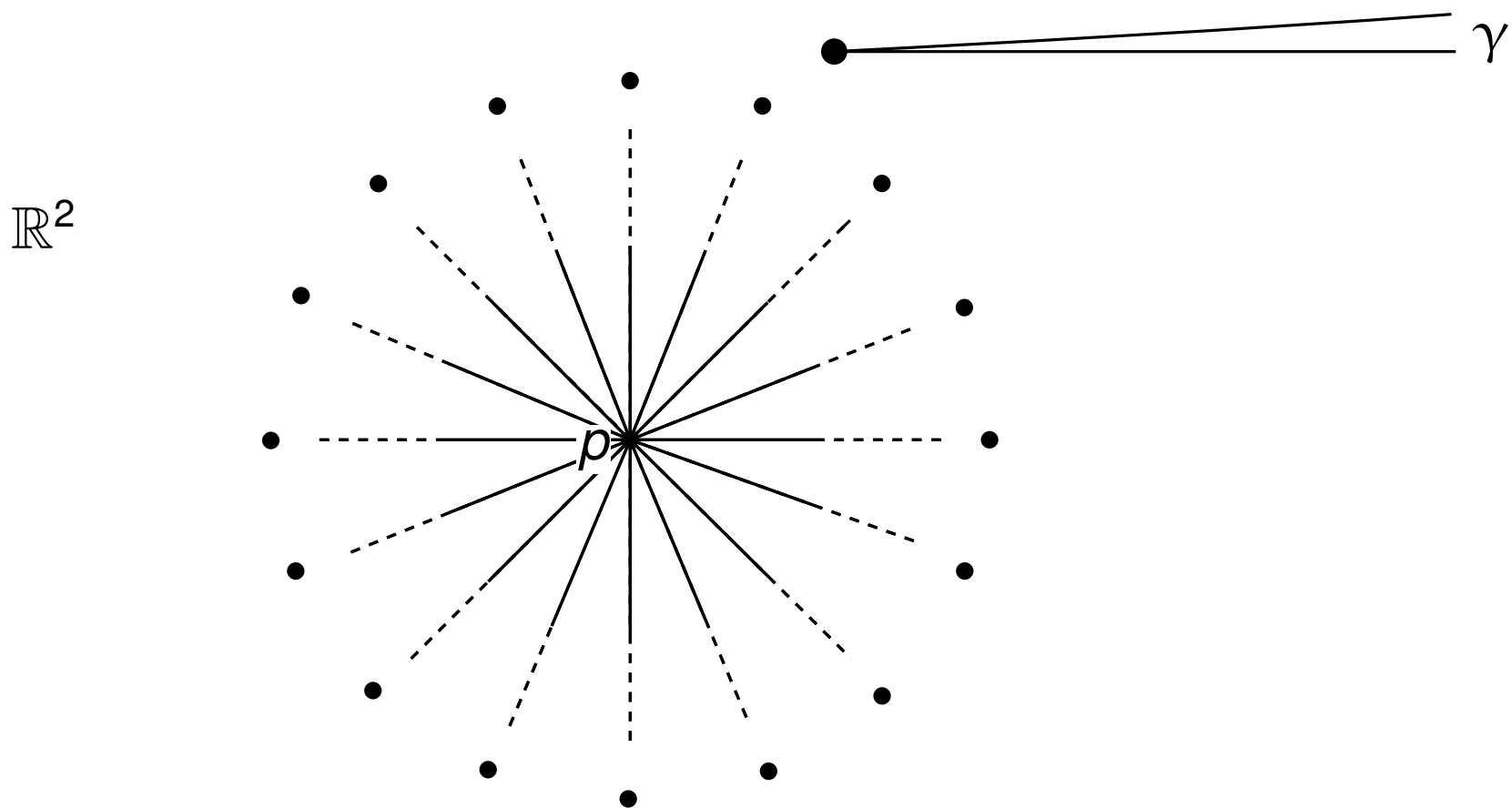
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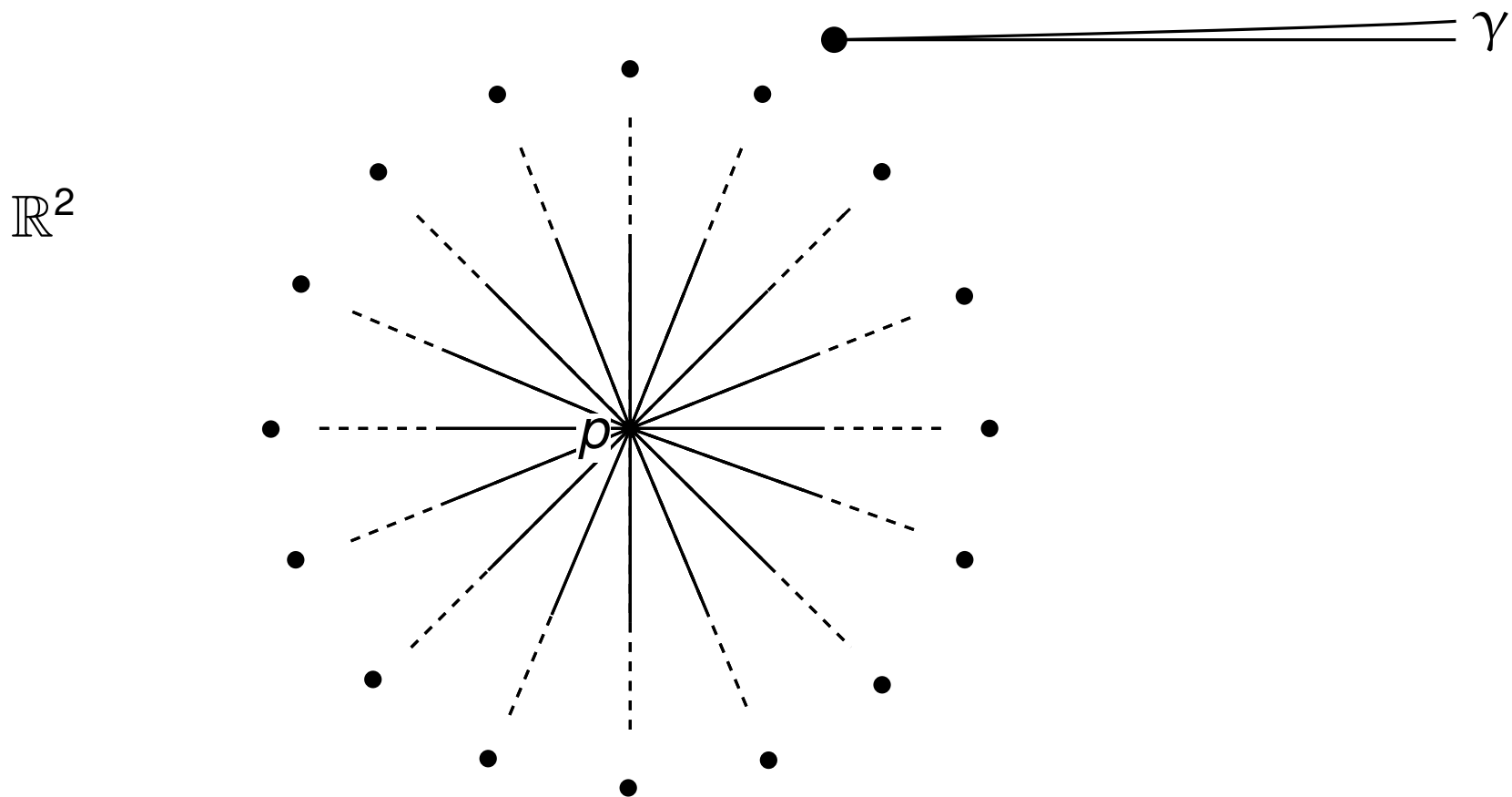
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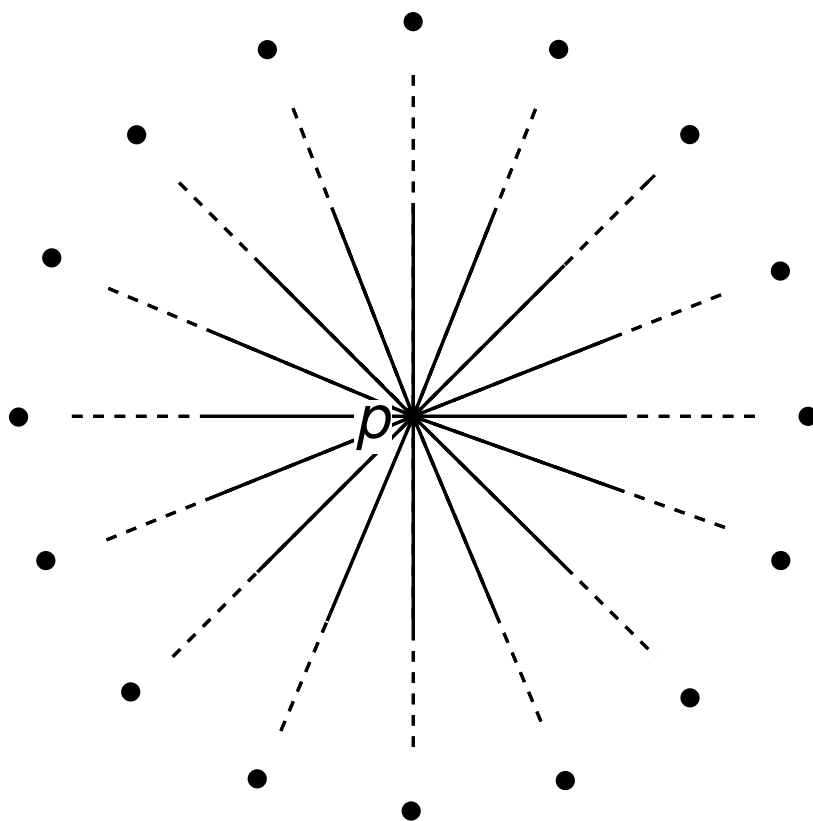


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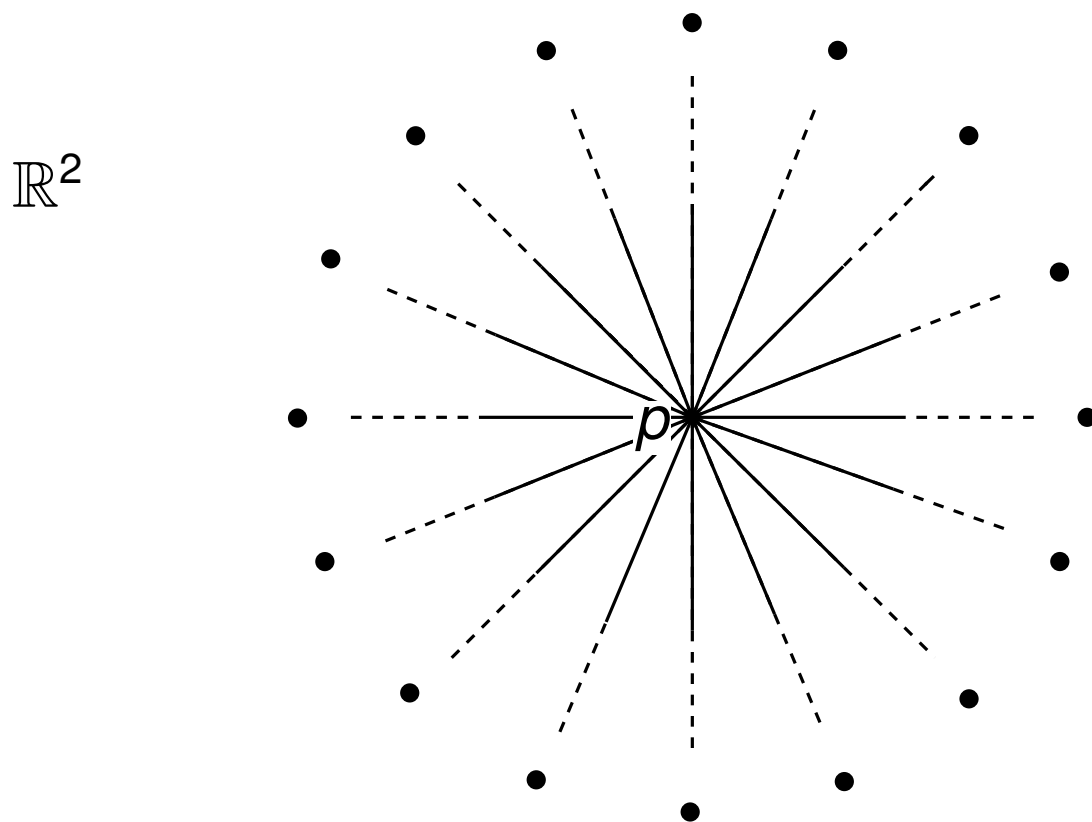
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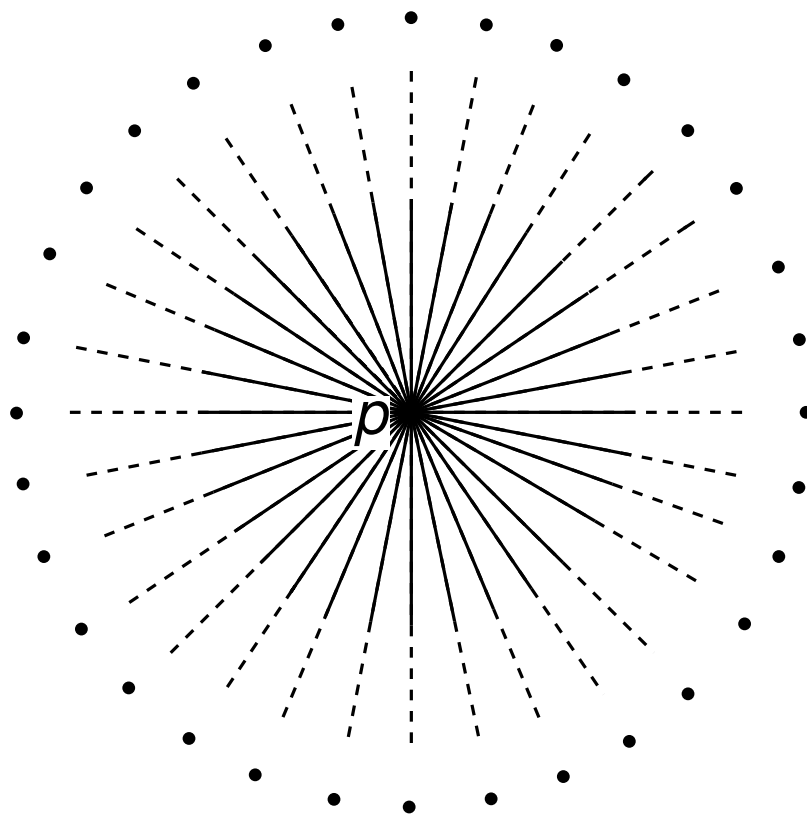


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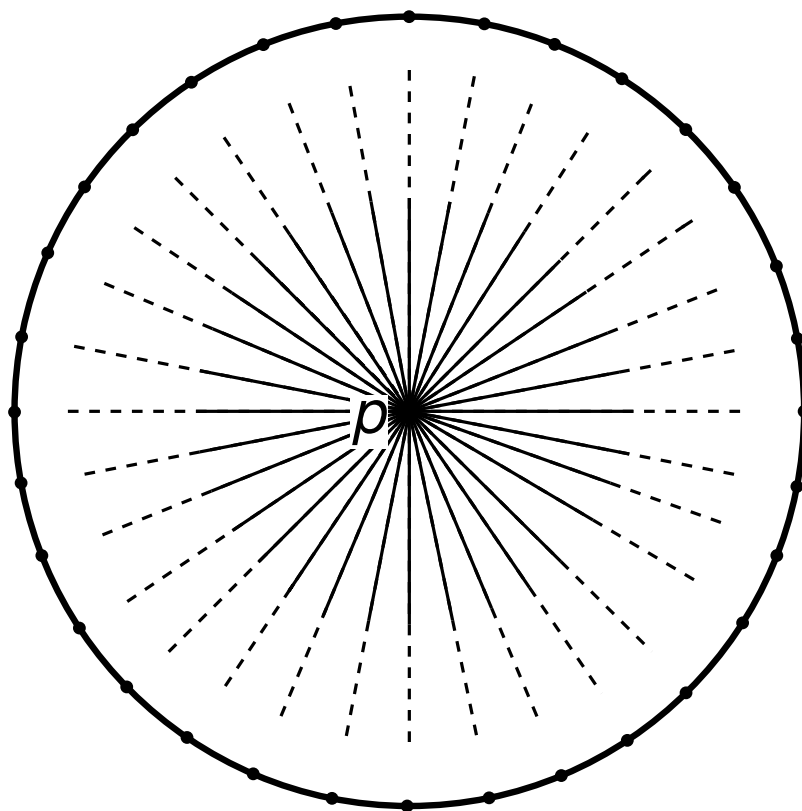


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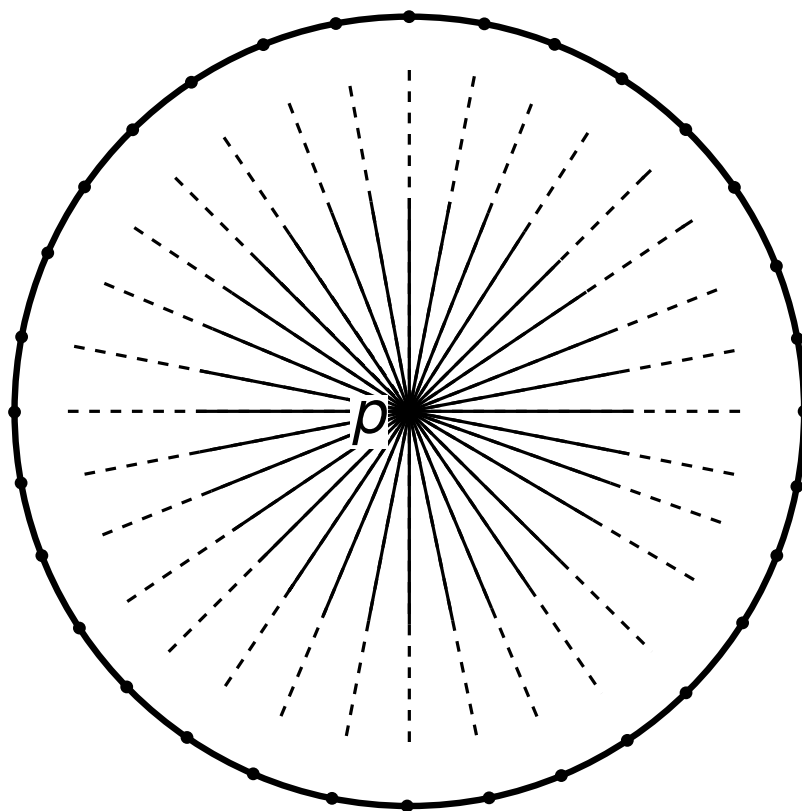
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$\partial \mathbb{R}^2 = S^1$

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Examples:

■ $\partial \mathbb{R}^2 = S^1,$

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Examples:

- $\partial \mathbb{R}^2 = S^1$,
- $\partial \mathbb{H}^2 = S^1$,
- $\partial T_{n \geq 3} = \mathcal{C}$ Cantor space,

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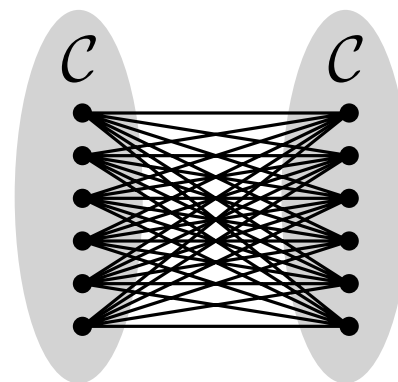
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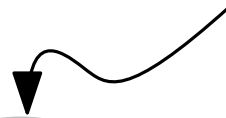
■ $X = X_1 \times X_2 \Rightarrow \partial X = \partial X_1 * \partial X_2$

■ $X = T_{n \geq 3} \times T_{m \geq 3} \Rightarrow \partial X = \mathcal{C} * \mathcal{C}$



Question: Suppose G acts nicely on a CAT(0) space X .
How are properties of G related to properties of ∂X ?

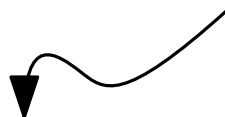
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CAT(0) group

geometrically



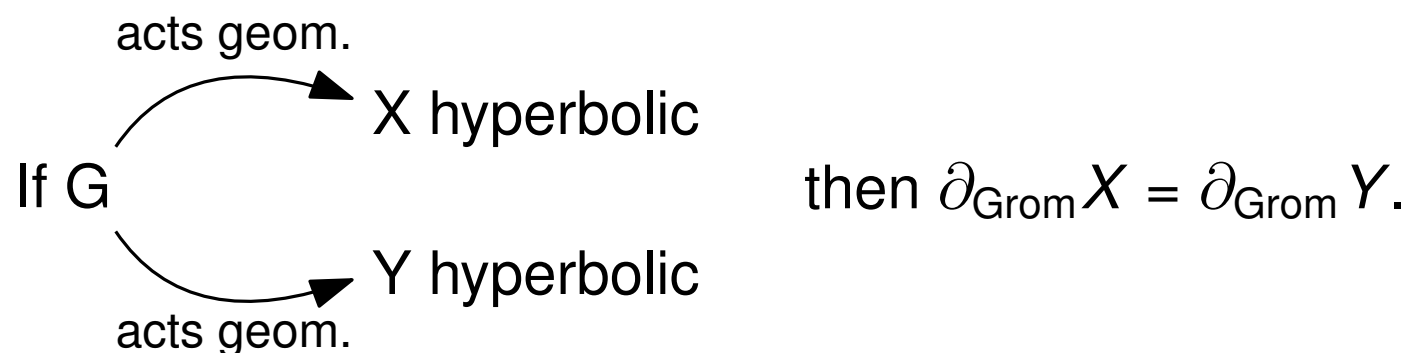
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Gromov boundary of hyperbolic groups

X hyperbolic space, $\partial_{\text{Grom}} X$ is defined similarly

X CAT(0) and hyperbolic $\Rightarrow \partial_{\text{Grom}} X = \partial X$.

Theorem (Gromov):



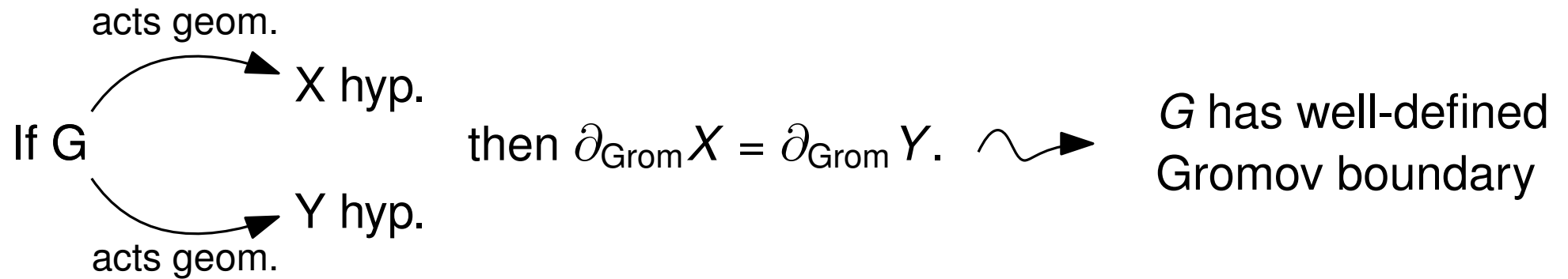
Corollary: If G is hyperbolic, then $\partial G := \partial X$ is well defined.

some space on which G acts geometrically

An arrow points from the text "some space on which G acts geometrically" to the X in the expression ∂X from the preceding corollary.

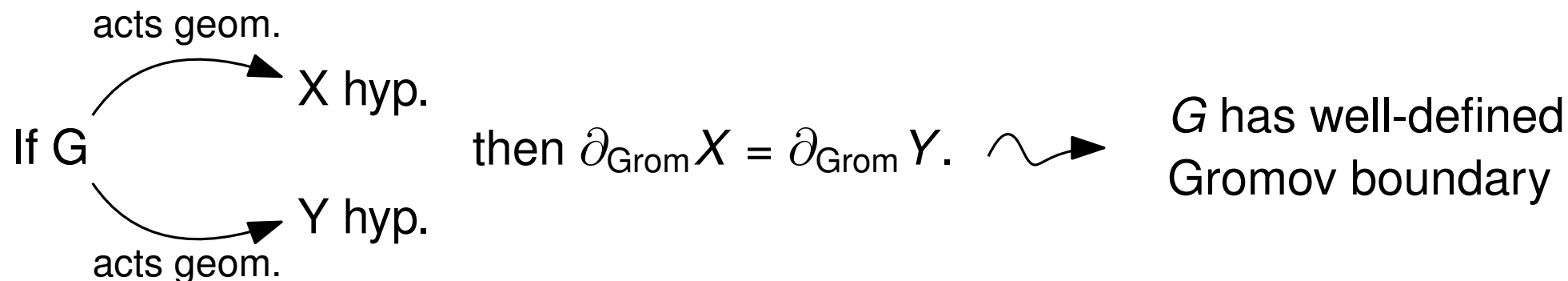
Visual boundary versus Gromov boundary

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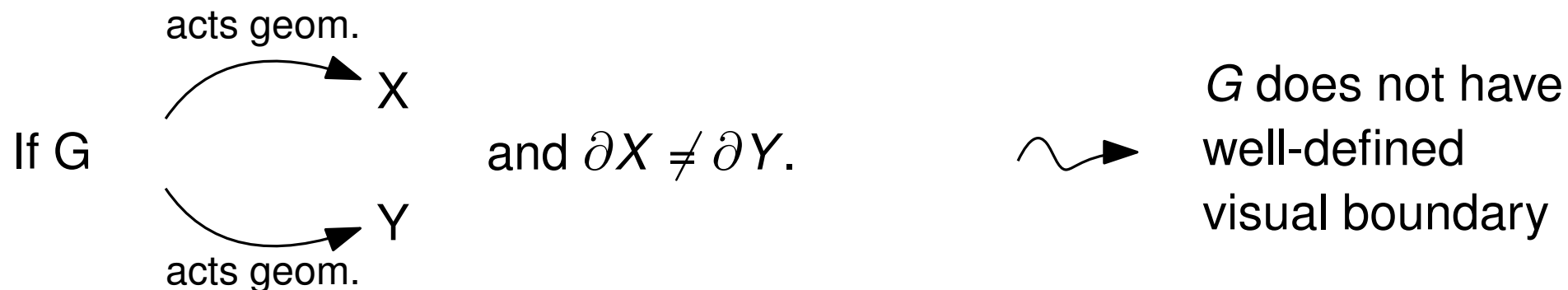


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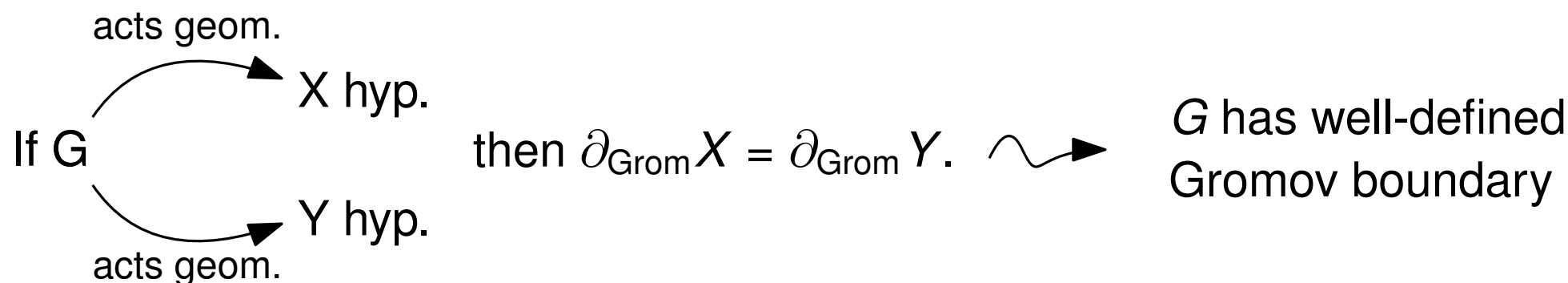


Theorem (Croke, Kleiner 00): $\exists G$ and CAT(0) spaces X, Y so that

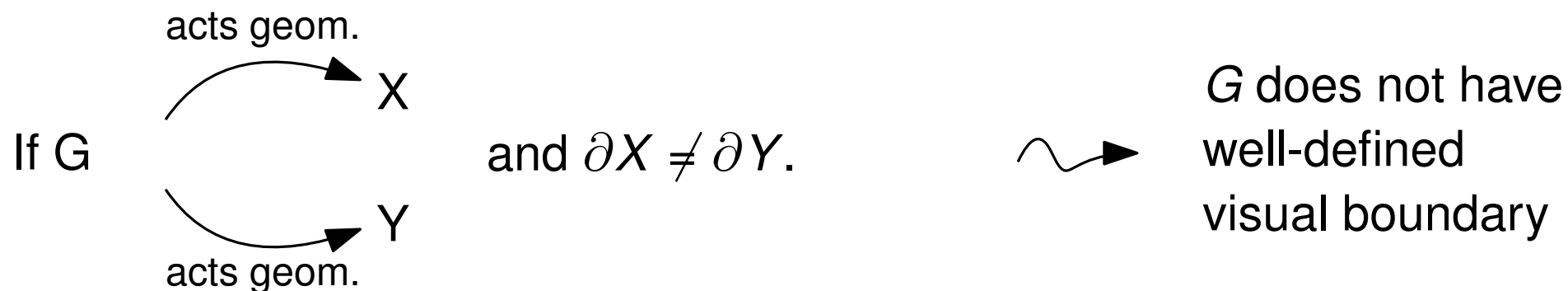


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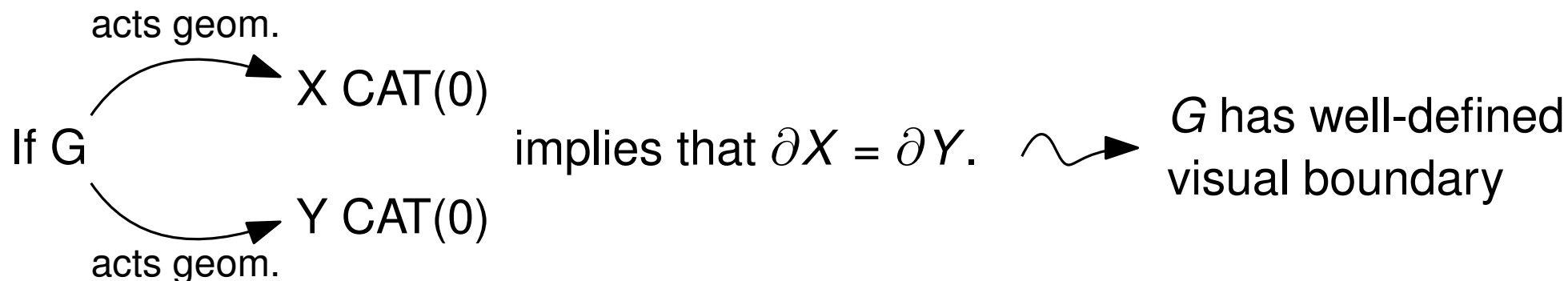
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Question: For which groups is the visual boundary well-defined?

Boundary rigidity

Definition (boundary rigidity): A CAT(0) group G is *boundary rigid* if

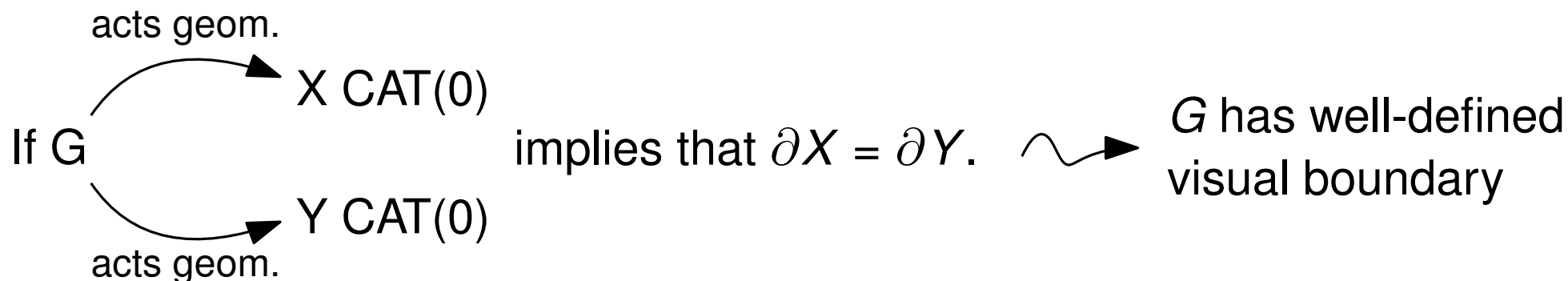


Examples of boundary rigid groups:

- $G = H \times \mathbb{Z}^n$ where H is hyperbolic (Bowers, Ruane 96)
- $G = H_1 \times H_2$ where H_1, H_2 are hyperbolic (Ruane 99)
- $G = H_1 \times H_2$ where H_1, H_2 are boundary rigid (Hosaka 2003)
- G acts geom. on a CAT(0) space that is relatively hyperbolic with respect to a family of flats. (Hruska–Kleiner 2005)

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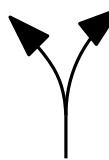
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Goal: Lattices in products of trees are boundary rigid!

Lattices in products of trees

Definition: A group G is a *lattice* in $T_n \times T_m$ if G acts geom. on $T_n \times T_m$.



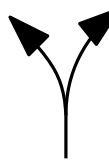
regular trees,
 $\deg \geq 3$

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A lattice G is

- *reducible* if G is virtually a direct product of 2 free groups
- *irreducible* otherwise.



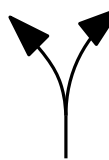
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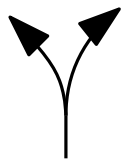
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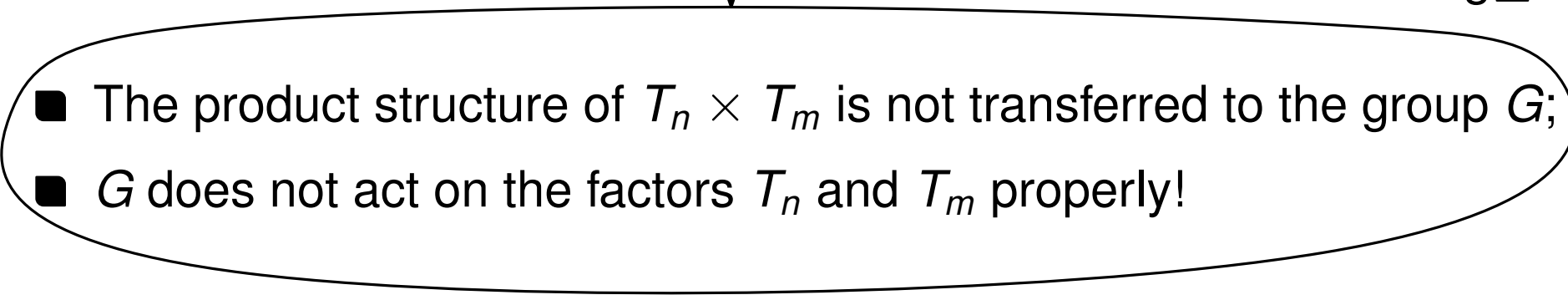
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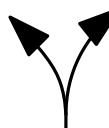
- 
- The product structure of $T_n \times T_m$ is not transferred to the group G ;
 - G does not act on the factors T_n and T_m properly!

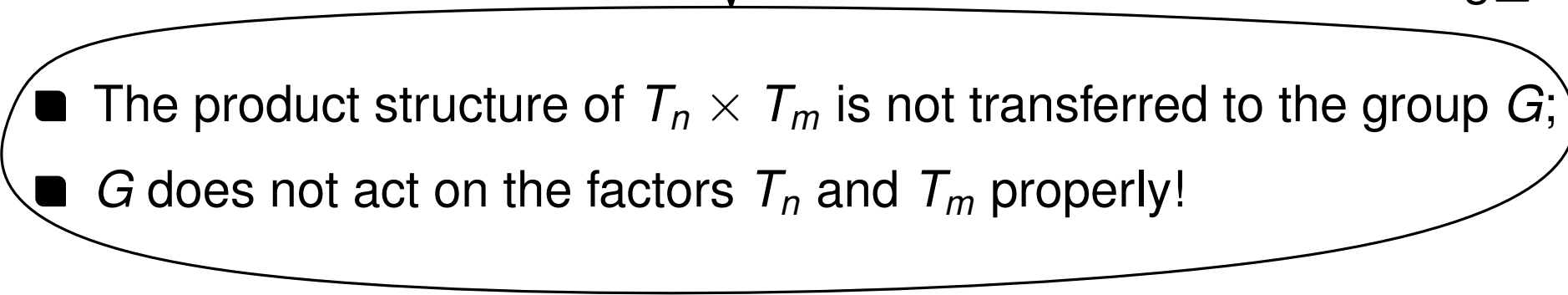
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Theorem: There exist irreducible lattices!

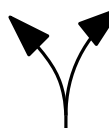
(They were first studied by Burger, Mozes, Wise)

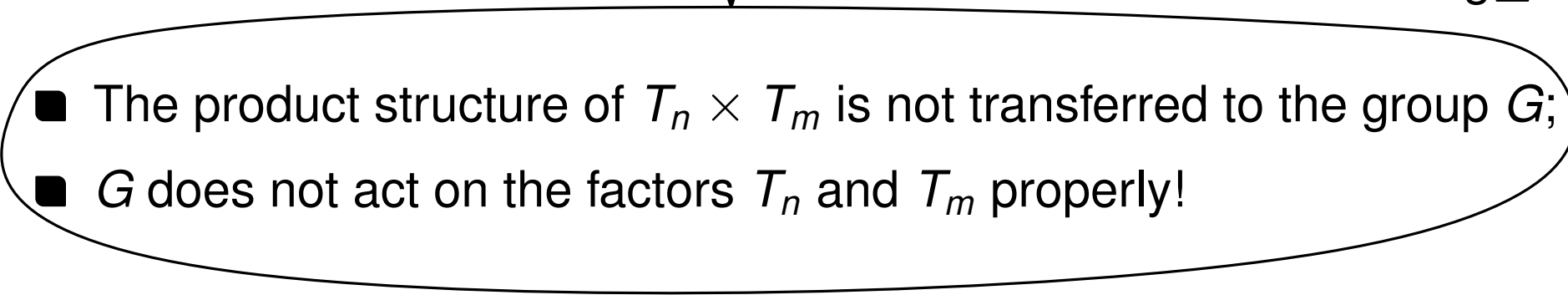
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Theorem: There exist irreducible lattices!

~> Burger, Mozes, Wise

Burger–Mozes 97

~> first example of a simple CAT(0) group

Lattices in products of trees are boundary rigid

Main Theorem:

$T_n \times T_m$ has a single orbit of vertices.

If G acts vertex-transitively and freely on $T_n \times T_m$ then G is boundary rigid.

In particular, $\partial G = \mathcal{C} * \mathcal{C}$.

regular trees,
 $\deg \geq 3$

Lattices in products of trees are boundary rigid

Main Theorem:

$T_n \times T_m$ has a single orbit of vertices.

If G acts vertex-transitively and freely on $T_n \times T_m$ then G is boundary rigid.

In particular, $\partial G = \mathcal{C} * \mathcal{C}$.

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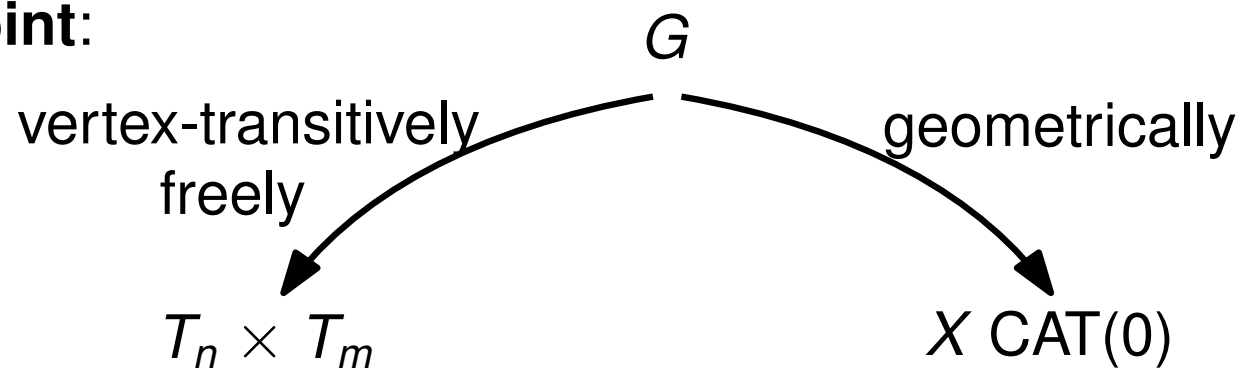
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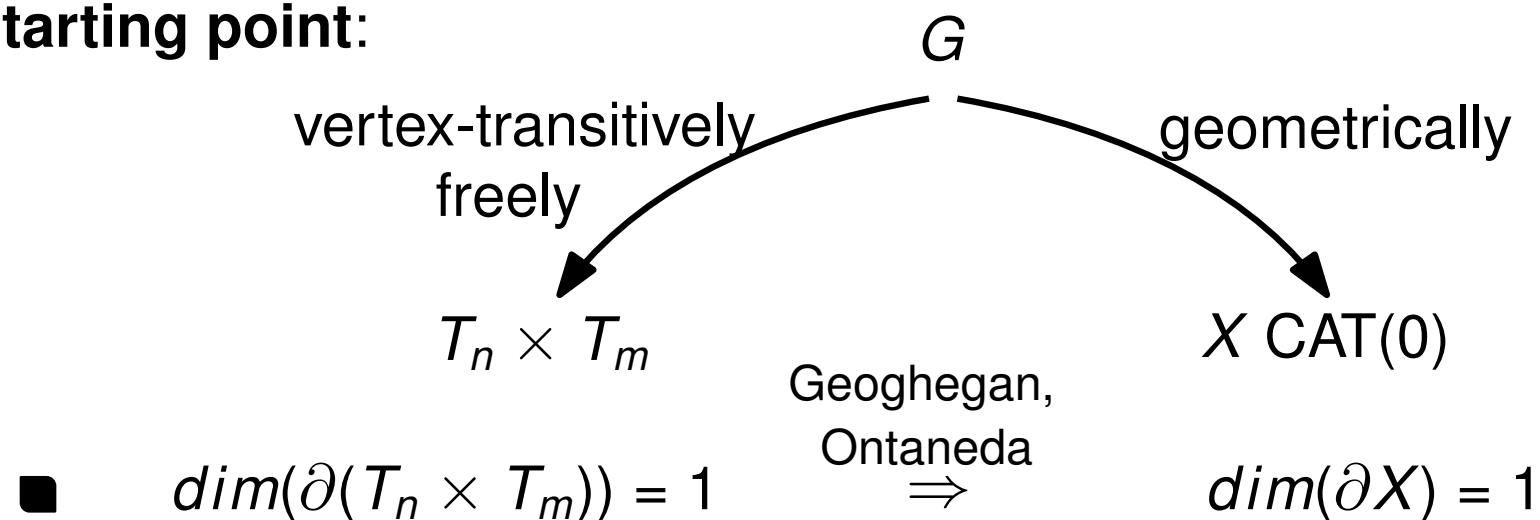
Proof sketch of Claim 1

Starting point:



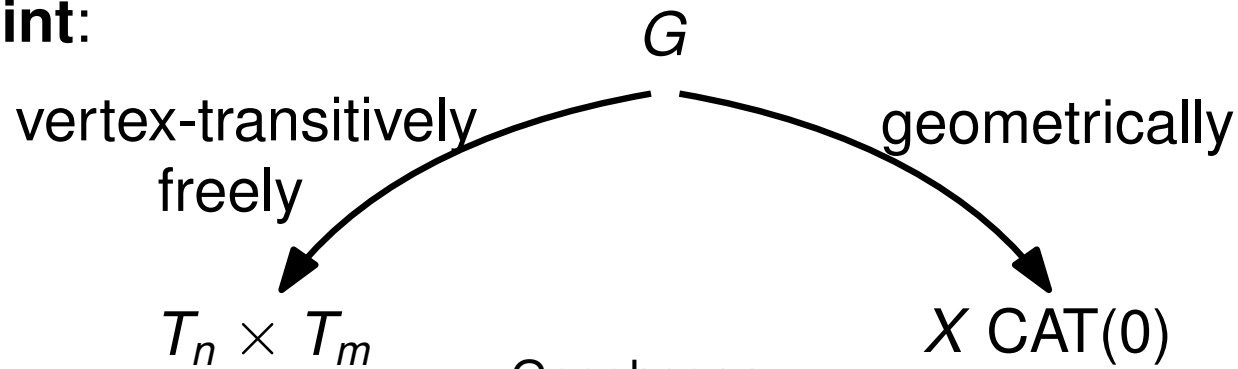
Proof sketch of Claim 1

Starting point:



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Starting point:



Geoghegan,
Ontaneda
 \Rightarrow

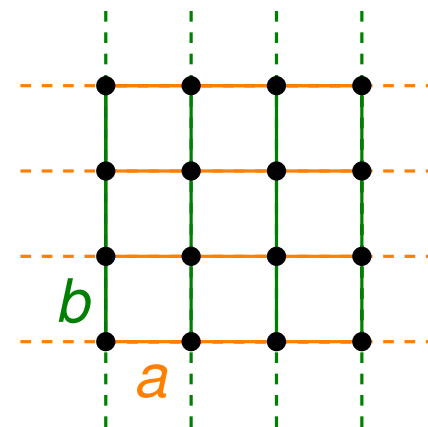
■ $\dim(\partial(T_n \times T_m)) = 1$

$\dim(\partial X) = 1$

■ vertex-transitively
freely

Wise
 \Rightarrow

$\exists a, b \in G$ s.t.
 $\langle a, b \rangle \cong \mathbb{Z}^2$ ↗ $F \subseteq X$ flat
|
convex



Proof sketch of Claim 1

Starting point:

geom.

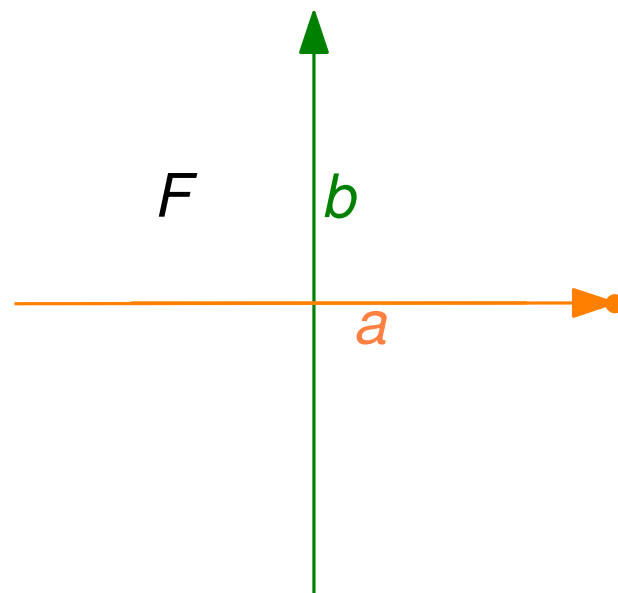
$G \curvearrowright X \text{ CAT}(0)$

■ $\dim(\partial X) = 1$

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$\langle a, b \rangle \cong \mathbb{Z}^2 \curvearrowright$

$F \subseteq X \text{ flat}$
 $\quad \quad \quad |$
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Strategy: Use Dynamics on Tits boundaries (Guralnik, Swenson, Ricks)

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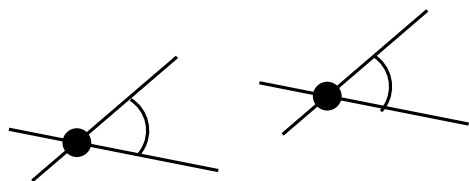
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Definition (Tits boundary): Let X CAT(0).

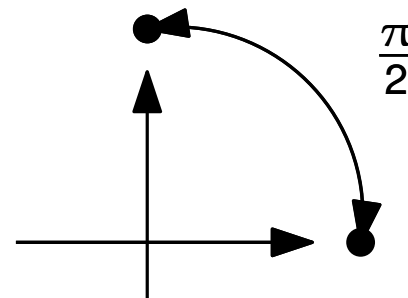
$\partial_T(X) := (\partial X, d_T)$ is the *Tits boundary* of X .

d_T
|
Tits distance

\mathbb{R}^2






$$\partial_T \mathbb{R}^2 = S^1$$






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Strategy: Use Dynamics on Tits boundaries (Guralnik, Swenson, Ricks)

space X	∂X	$\partial_T X$
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


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


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


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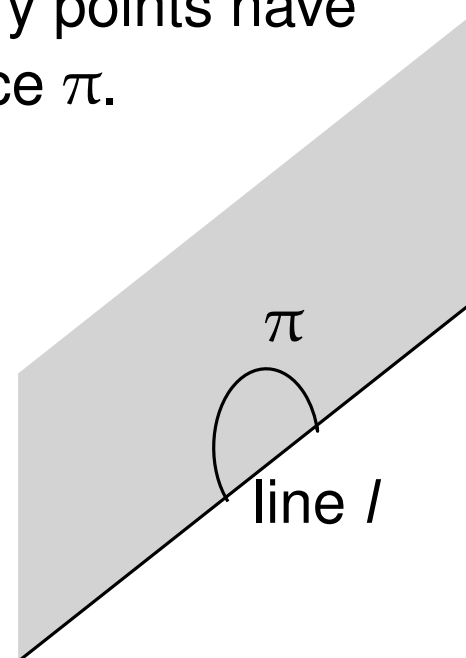
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a line bounds a half flat iff its boundary points have Tits distance π .






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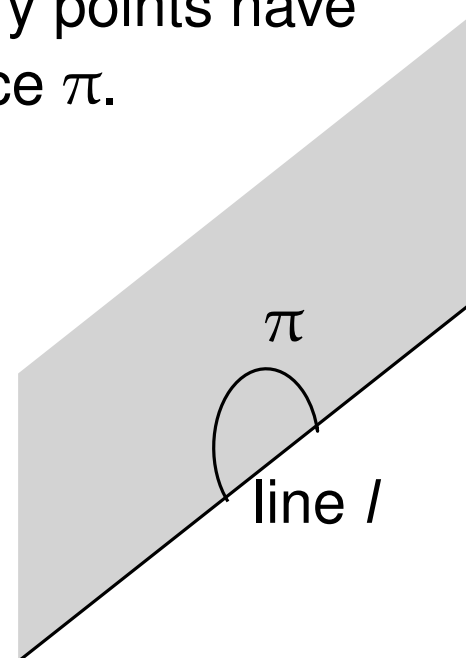
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


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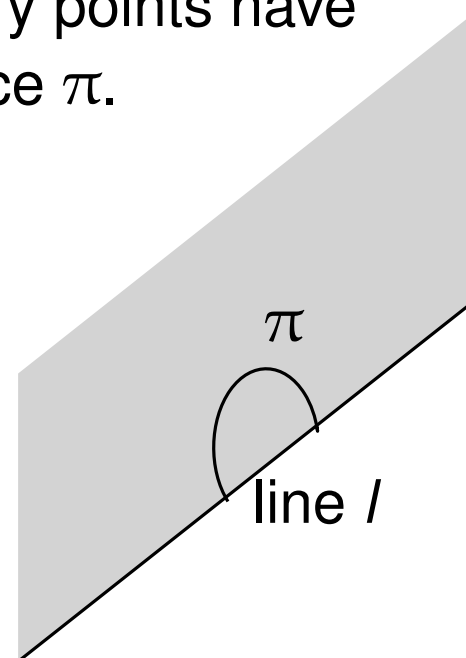
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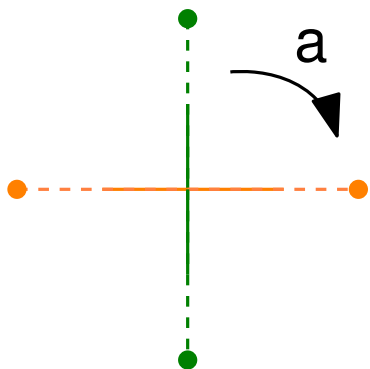
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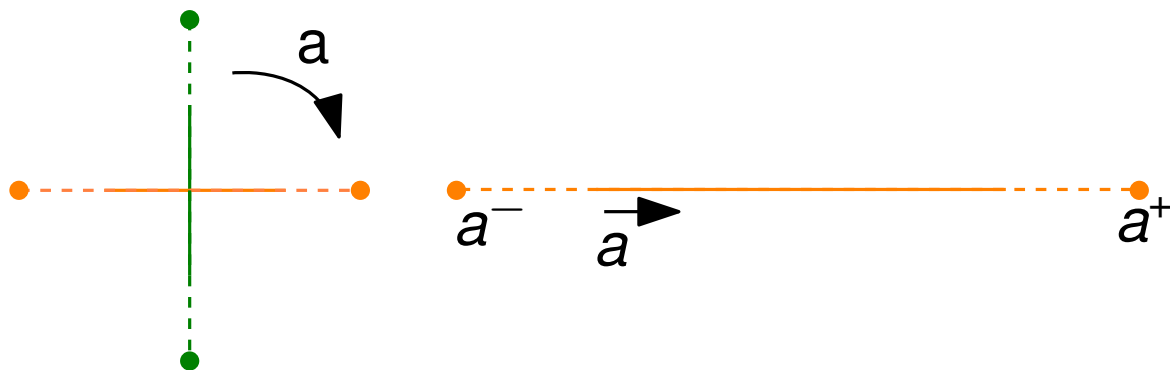


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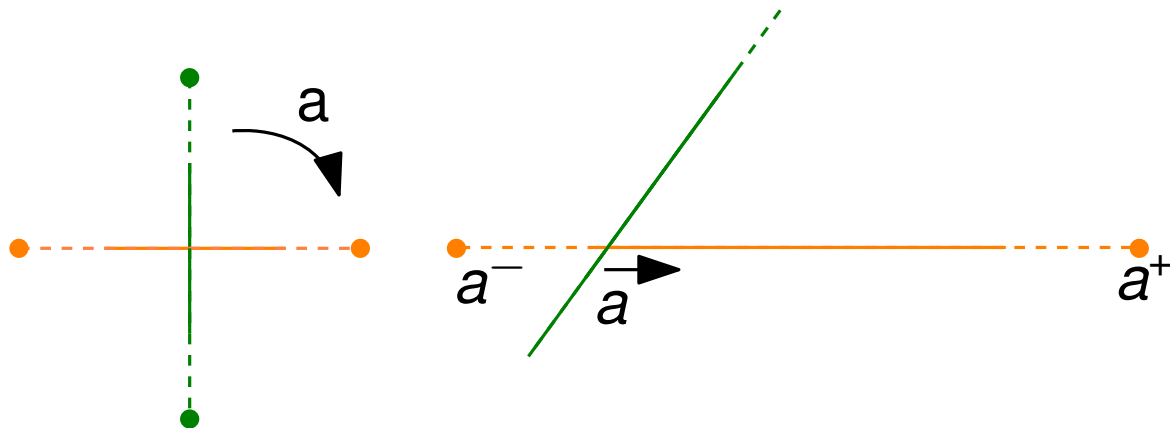
\mathbb{R}^2



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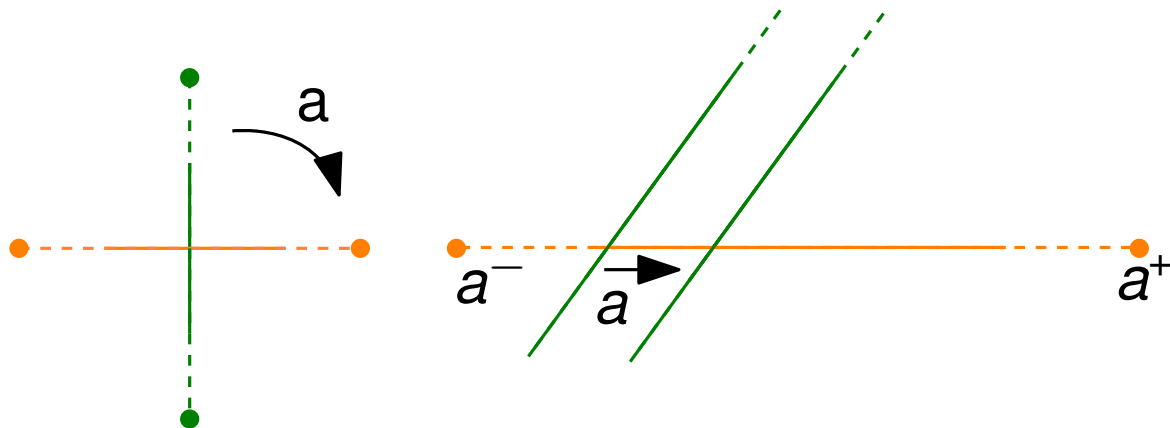


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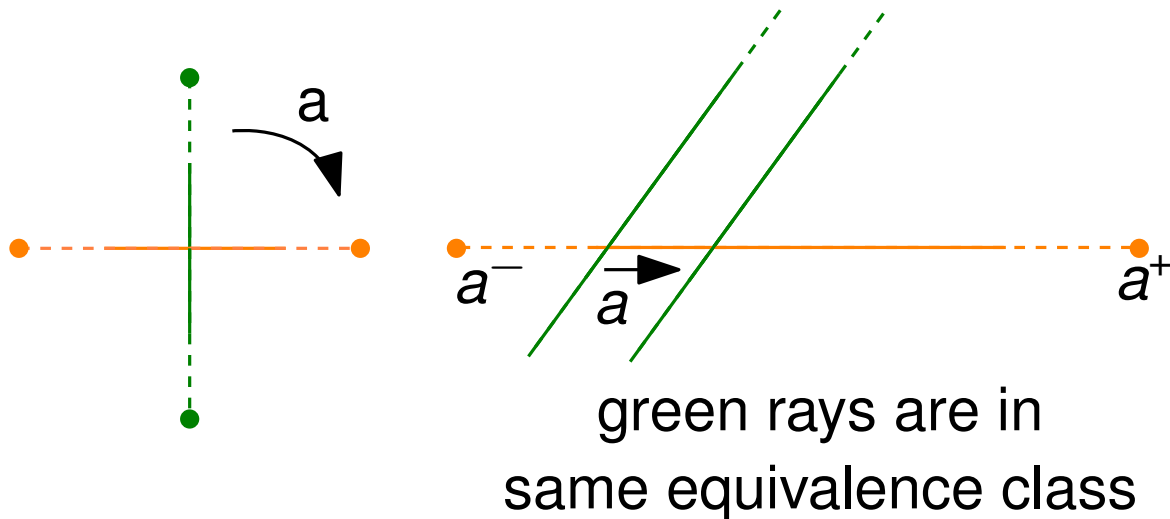


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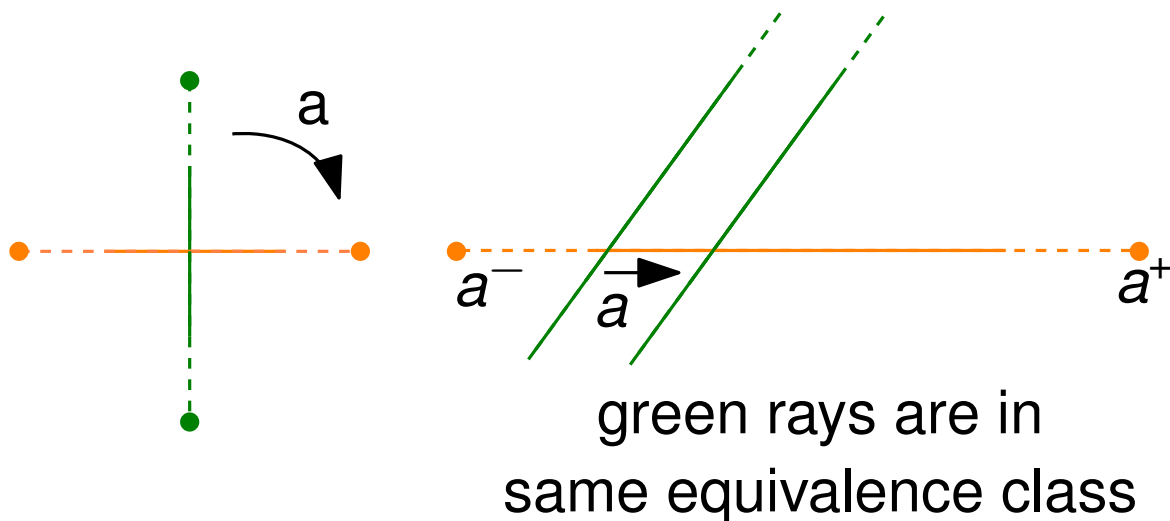


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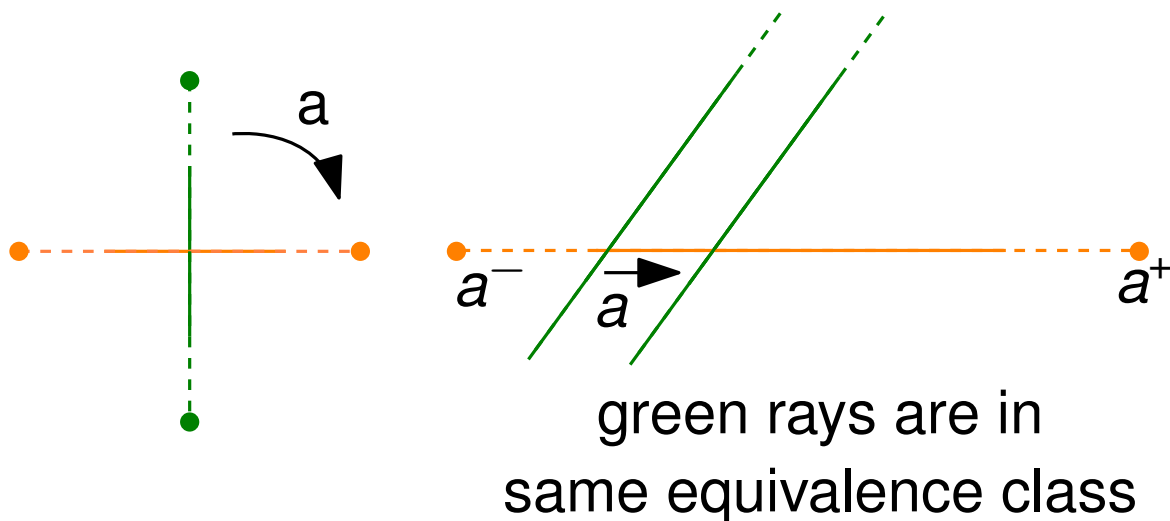
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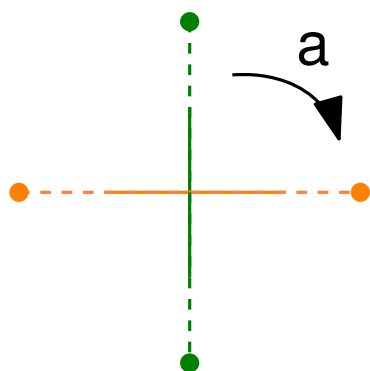


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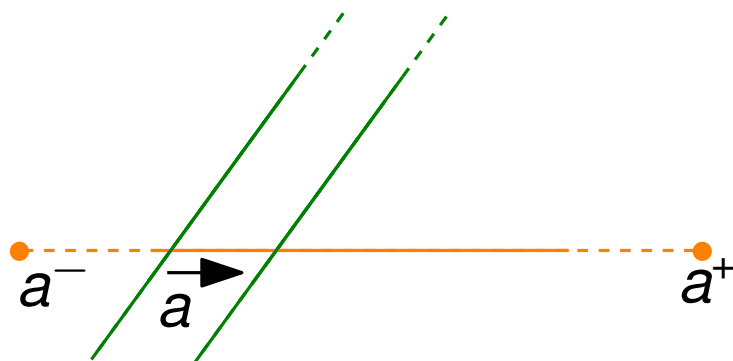
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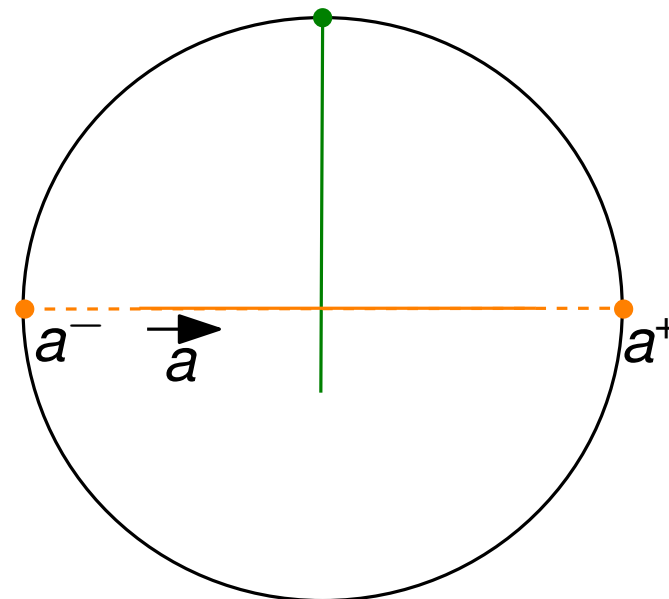
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green rays are in
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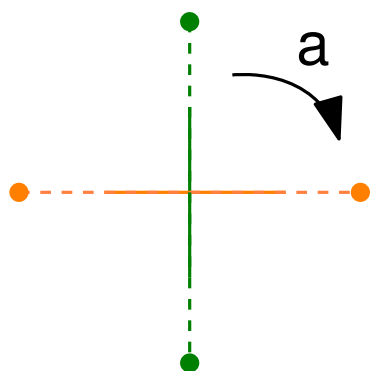
\mathbb{H}^2



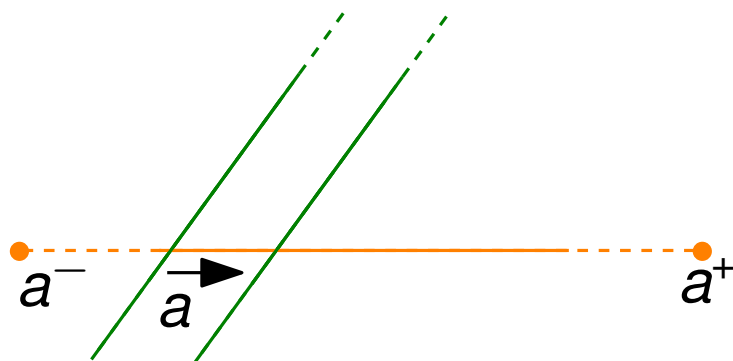
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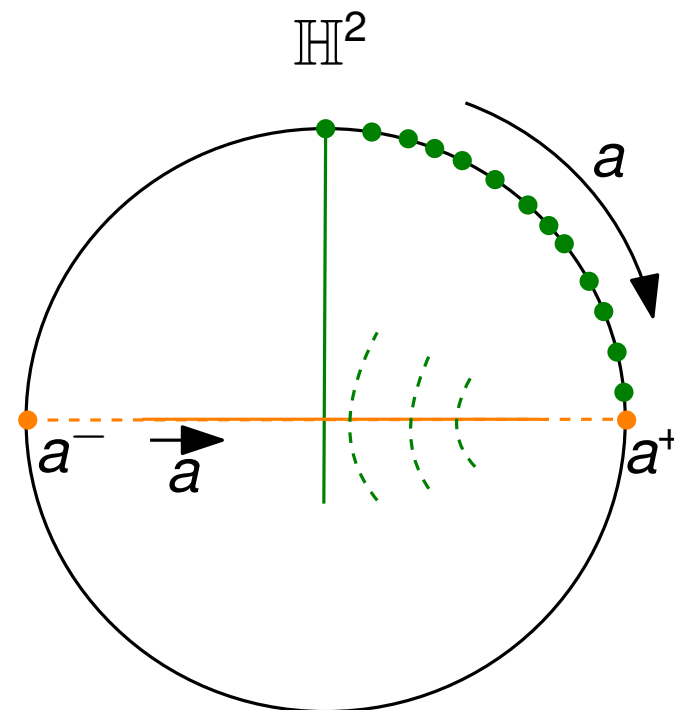
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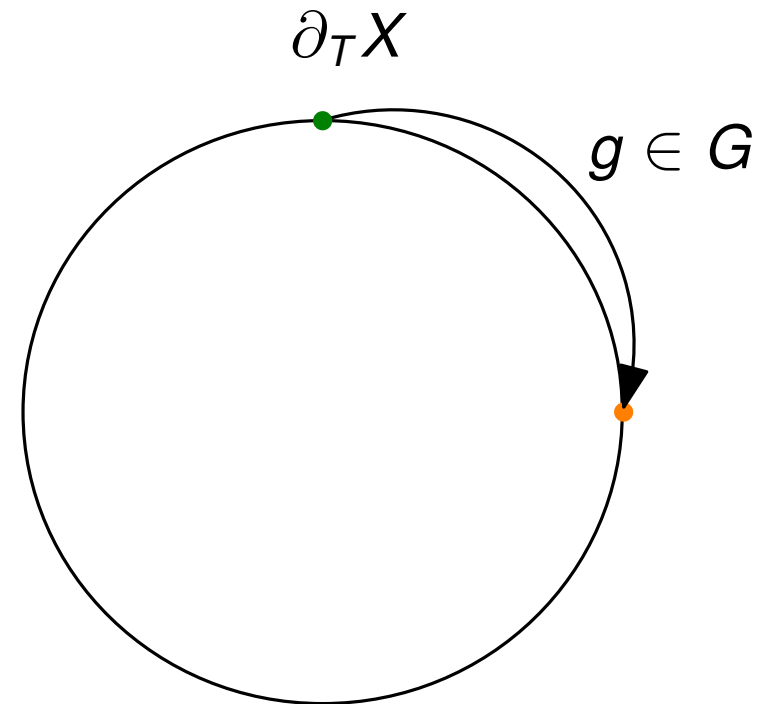
North-South-dynamics



$$\begin{aligned} a^n a^- &\xrightarrow{n \rightarrow \infty} a^-, \\ a^n \bar{\gamma} &\xrightarrow{n \rightarrow \infty} a^+ \\ &\text{for all } \bar{\gamma} \in \partial X - \{a^-\} \end{aligned}$$

Proof sketch of Claim 1

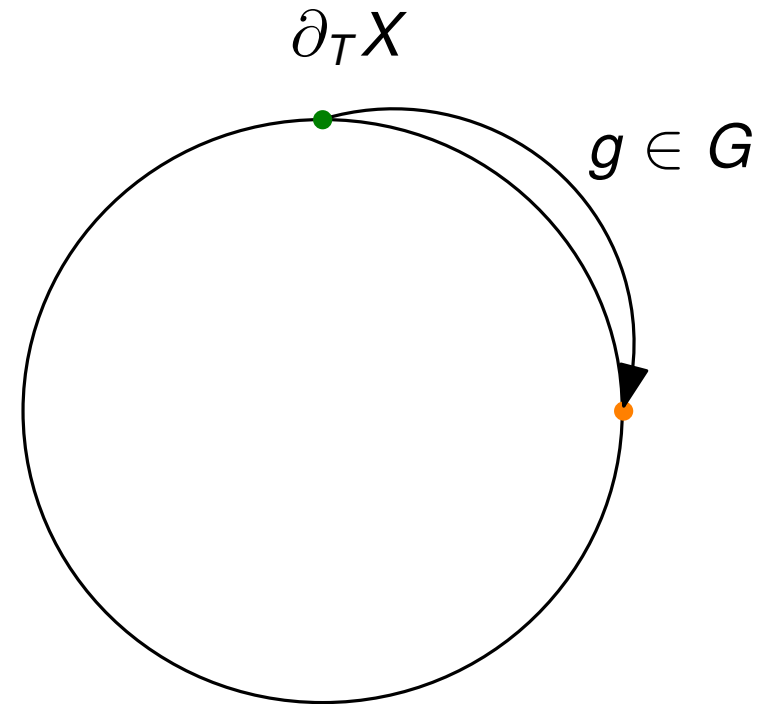
Generalize dynamics on boundaries (Guralnik–Swenson, 2013):



Proof sketch of Claim 1

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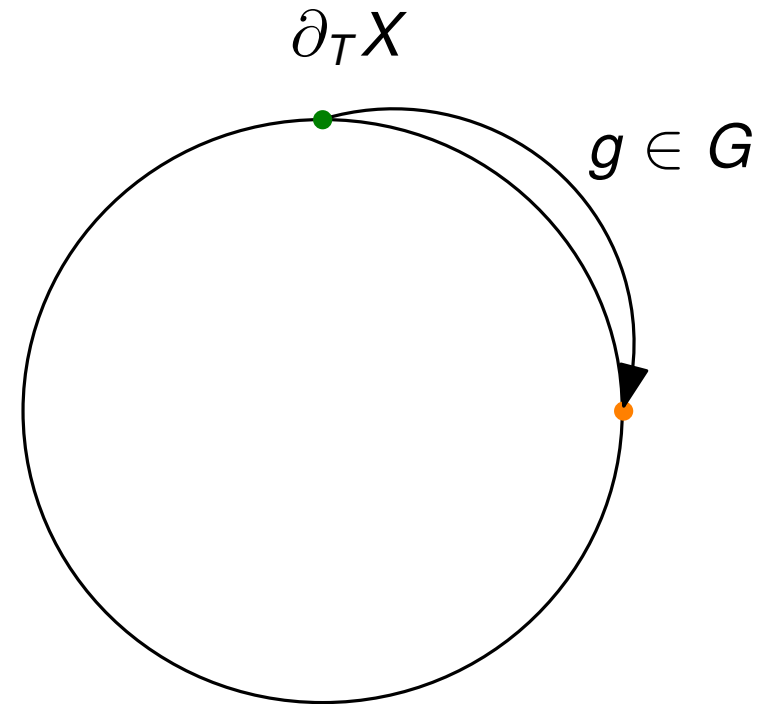
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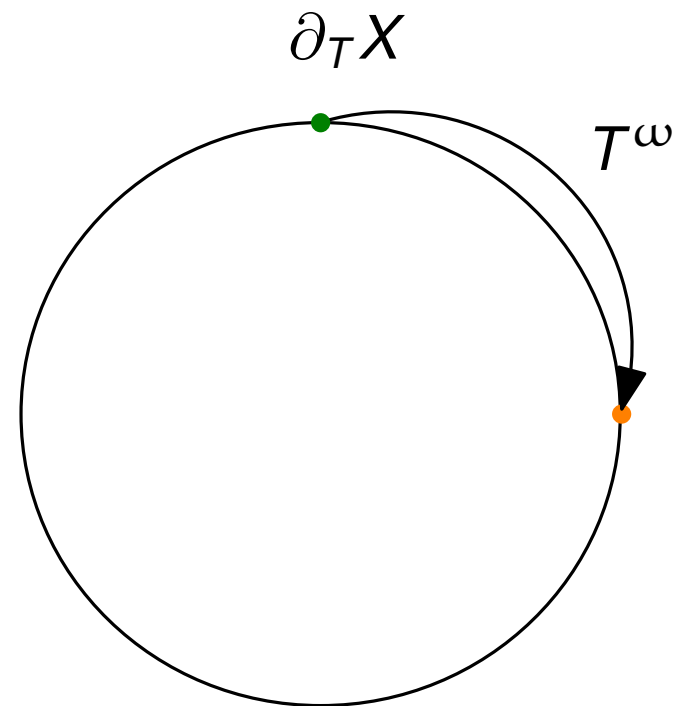
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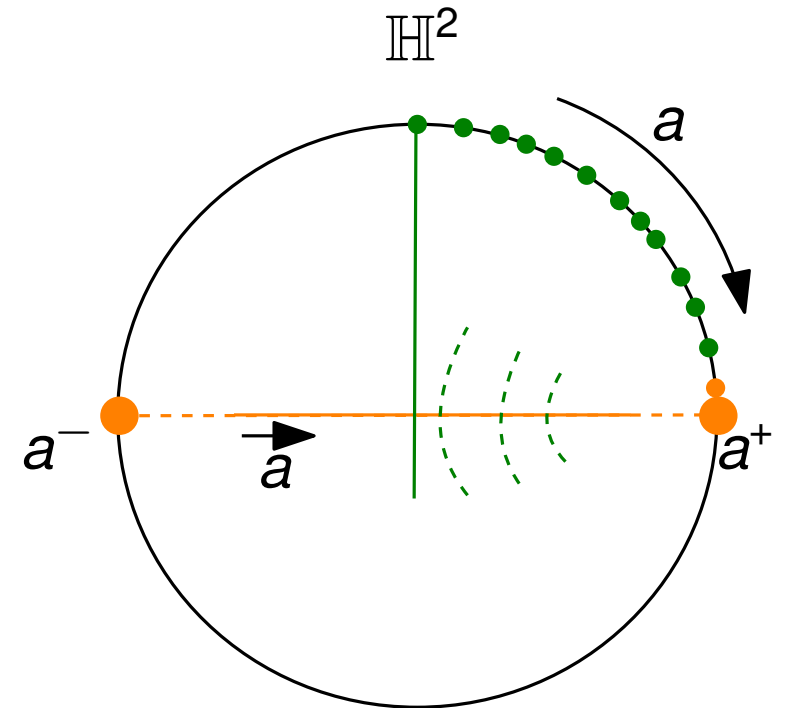
$$\beta G \curvearrowright \partial_T X$$

$$\omega \mapsto T^\omega : \partial_T X \rightarrow \partial_T X$$



Proof sketch of Claim 1

Theorem (a higher-dimensional version of North-South dynamics):



North-South-dynamics

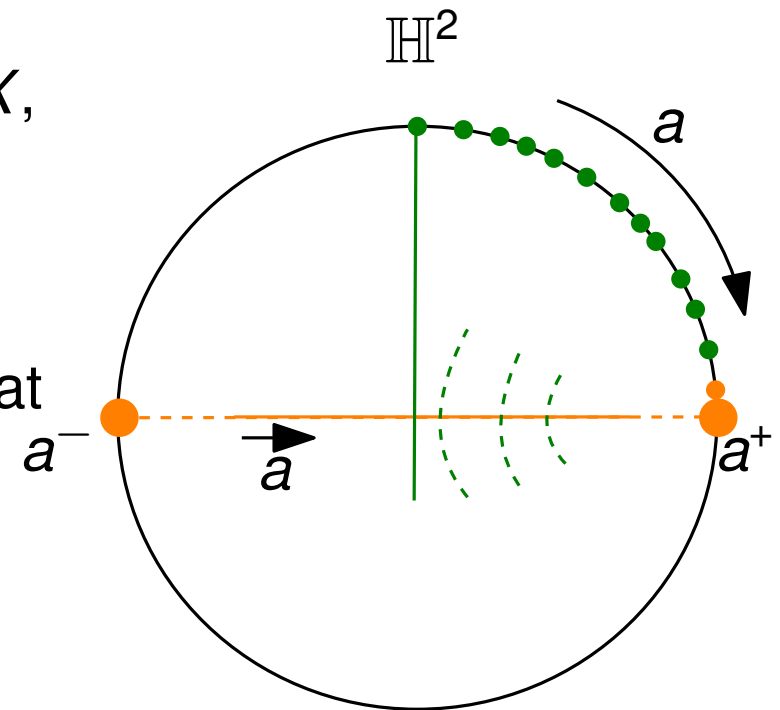
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Theorem (a higher-dimensional version of North-South dynamics):
Suppose that

- G acts geometrically on a CAT(0) space X ,
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- $\exists H < G, H \cong \mathbb{Z}^{d+1}$.

Then $\exists (d+1)$ -flat $F \subseteq X$ and $\omega \in \beta G$ so that

- F is H -invariant, $\underbrace{\quad}_{\text{convex}}$
- $T^\omega(\partial_T X) = \partial_T F$,
- $T^\omega|_{\partial_T F} = \text{id}$.



North-South-dynamics

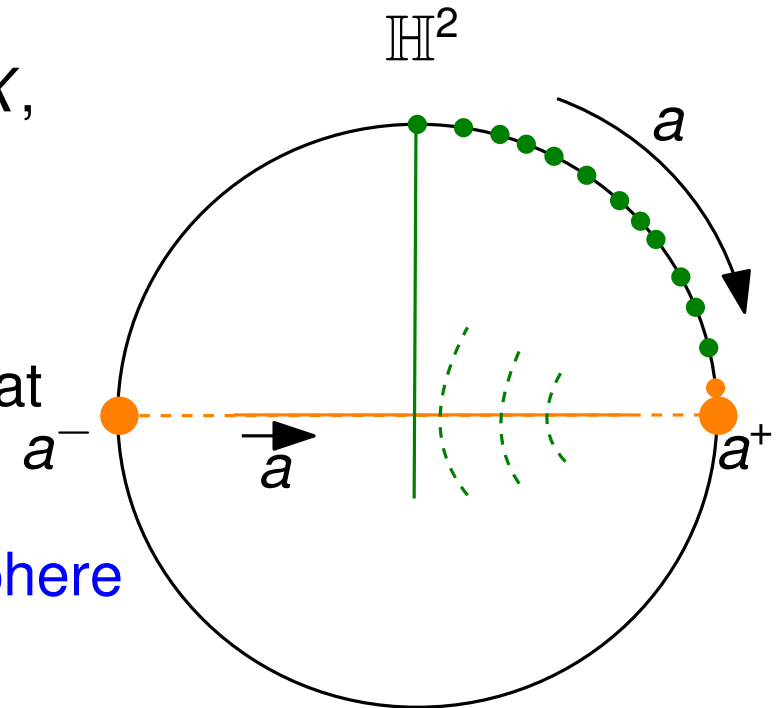
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- $T^\omega(\partial_T X) = \partial_T F$, ← attracting top-dim. sphere
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North-South-dynamics

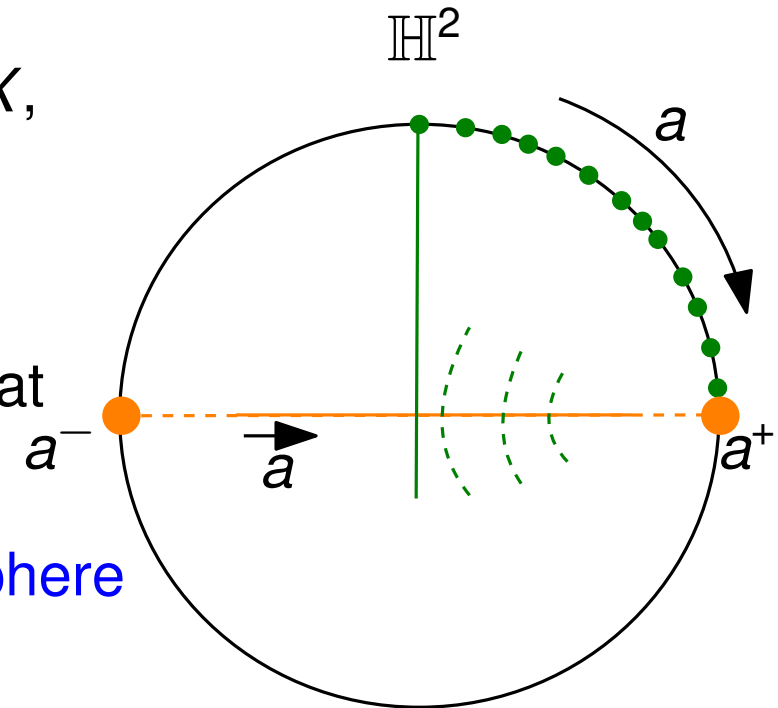
Proof sketch of Claim 1

Theorem (a higher-dimensional version of North-South dynamics):
Suppose that

- G acts geometrically on a CAT(0) space X ,
- $d := \dim(\partial_T X)$,
- $\exists H < G, H \cong \mathbb{Z}^{d+1}$.

Then $\exists (d+1)$ -flat $F \subseteq X$ and $\omega \in \beta G$ so that

- F is H -invariant, \searrow
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North-South-dynamics

X proper hyperbolic $\Rightarrow \partial_T X$ is 0-dimensional

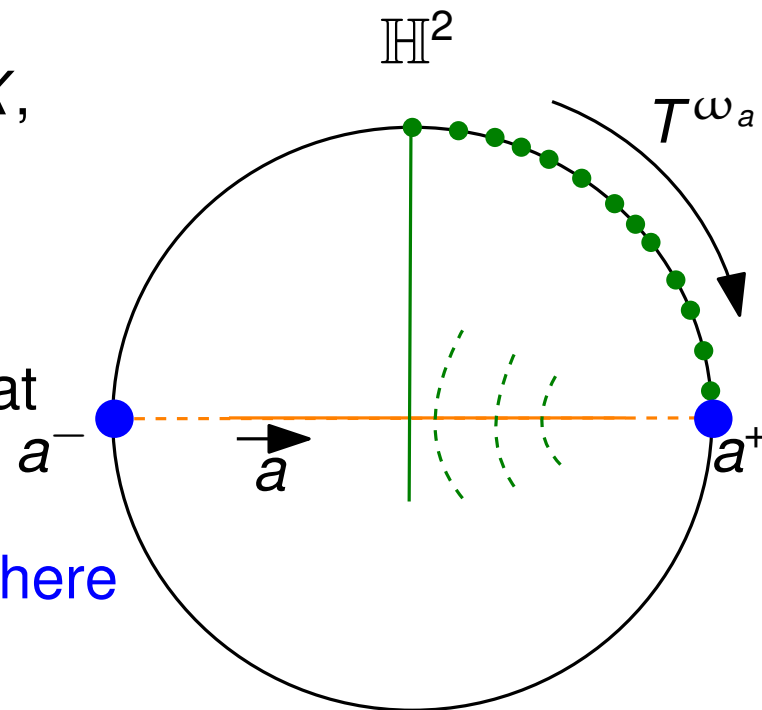
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North-South-dynamics

X proper hyperbolic $\Rightarrow \partial_T X$ is 0-dimensional
endvertices of lines are top-dimensional spheres

Proof sketch of Claim 1

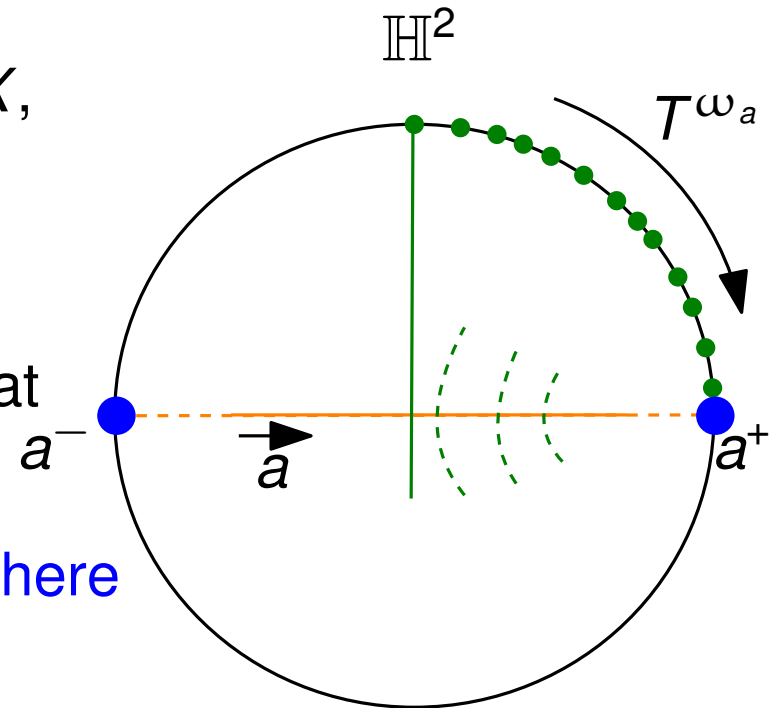
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North-South-dynamics

Proof sketch of Claim 1

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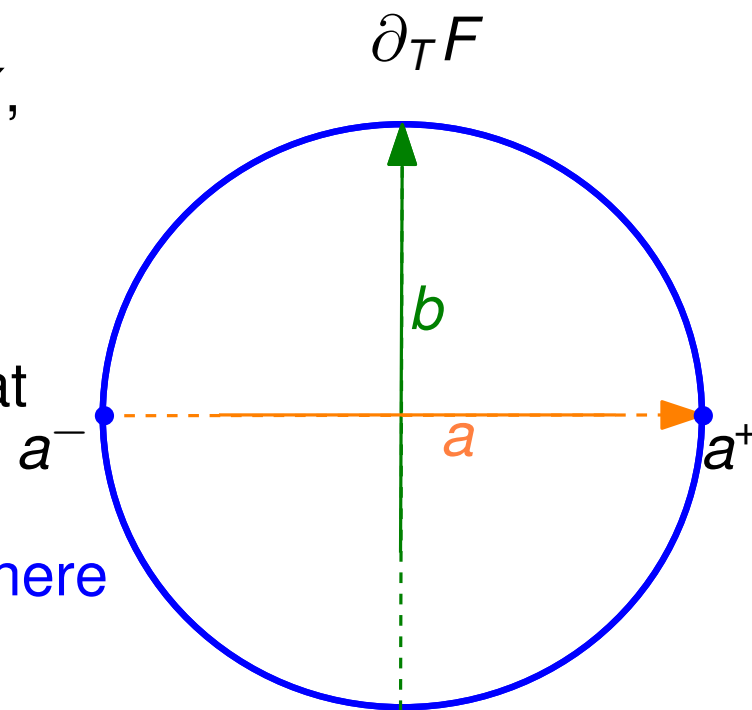
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$d = 1$: $\exists a, b \in G$ s.t.

$\langle a, b \rangle \cong \mathbb{Z}^2 \curvearrowright F \subseteq X$ flat
 $\underbrace{\quad}_{\text{convex}}$



Proof sketch of Claim 1

Theorem (a higher-dimensional version of North-South dynamics):
Suppose that

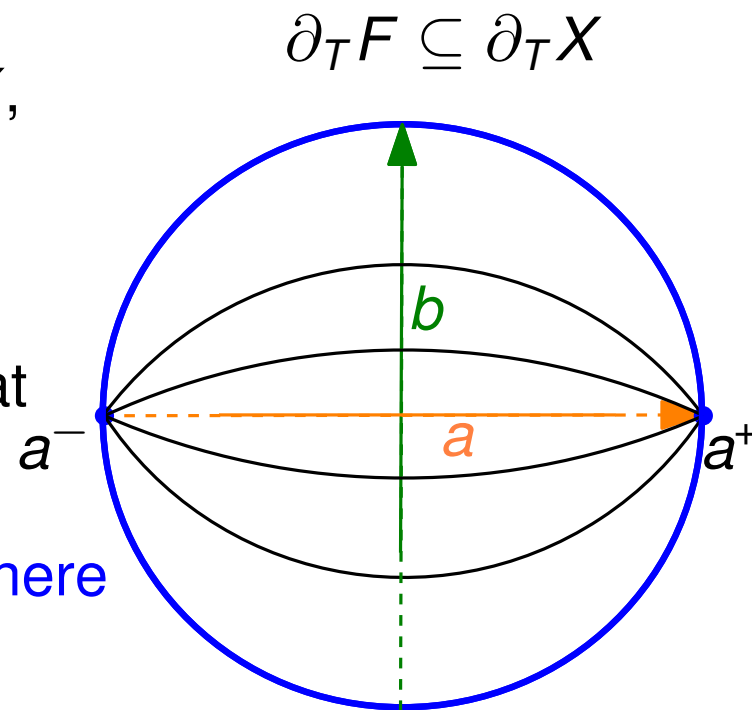
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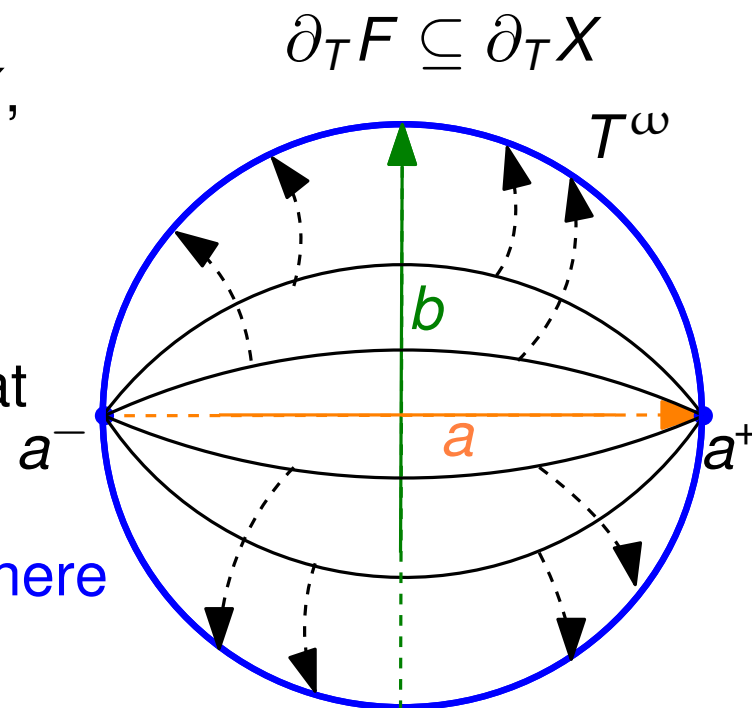
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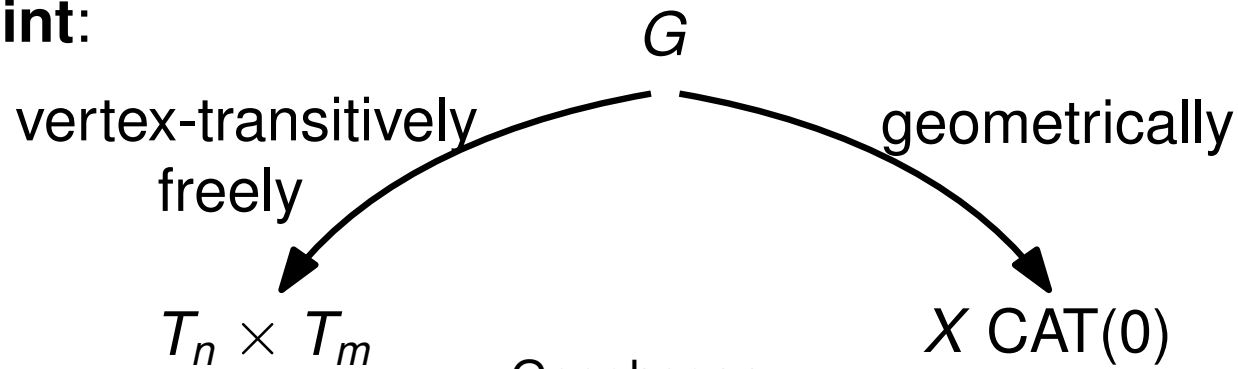
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Proof sketch of Claim 1

Starting point:



Geoghegan,
Ontaneda
 \Rightarrow

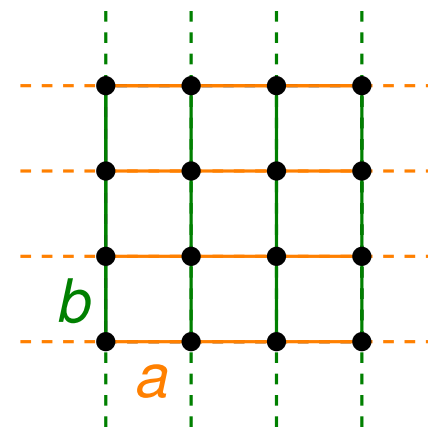
■ $\dim(\partial(T_n \times T_m)) = 1$

$\dim(\partial X) = 1$

■ vertex-transitively
freely

Wise
 \Rightarrow

$\exists a, b \in G$ s.t.
 $\langle a, b \rangle \cong \mathbb{Z}^2$ ↗ $F \subseteq X$ flat
|
convex



Proof sketch of Claim 1

Starting point:

geom.

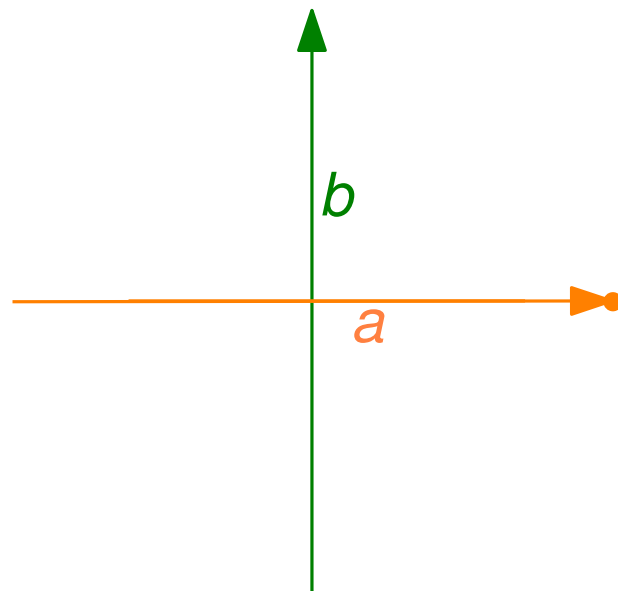
$G \curvearrowright X \text{ CAT}(0)$

■ $\dim(\partial X) = 1$

■ $\exists a, b \in G \text{ s.t.}$

$\langle a, b \rangle \cong \mathbb{Z}^2 \curvearrowright$

$F \subseteq X \text{ flat}$
|
 convex



Proof sketch of Claim 1

Starting point:

geom.

$G \curvearrowright X \text{ CAT}(0)$

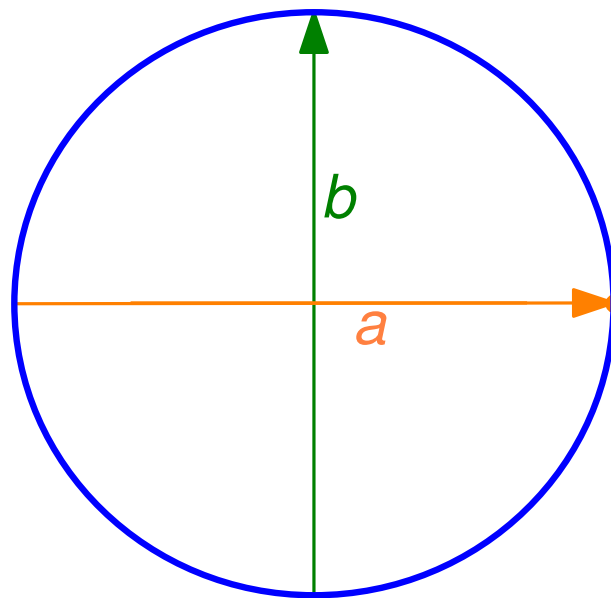
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$F \subseteq X$ flat
|
convex

$$\partial_T F \subseteq \partial_T X$$



Proof sketch of Claim 1

Starting point:

geom.

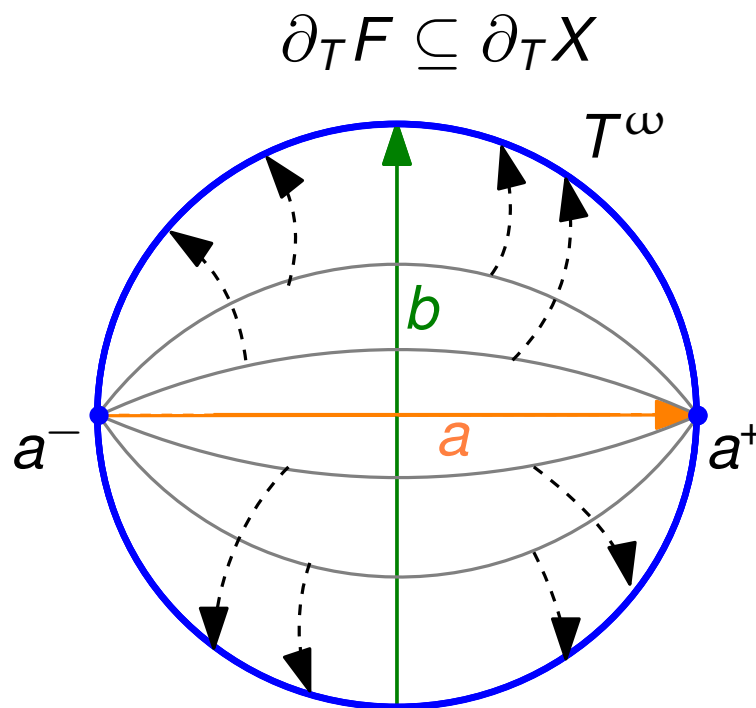
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|
convex



$\Rightarrow \partial_T F$ is an attracting top-dimensional sphere!

Proof sketch of Claim 1

Starting point:

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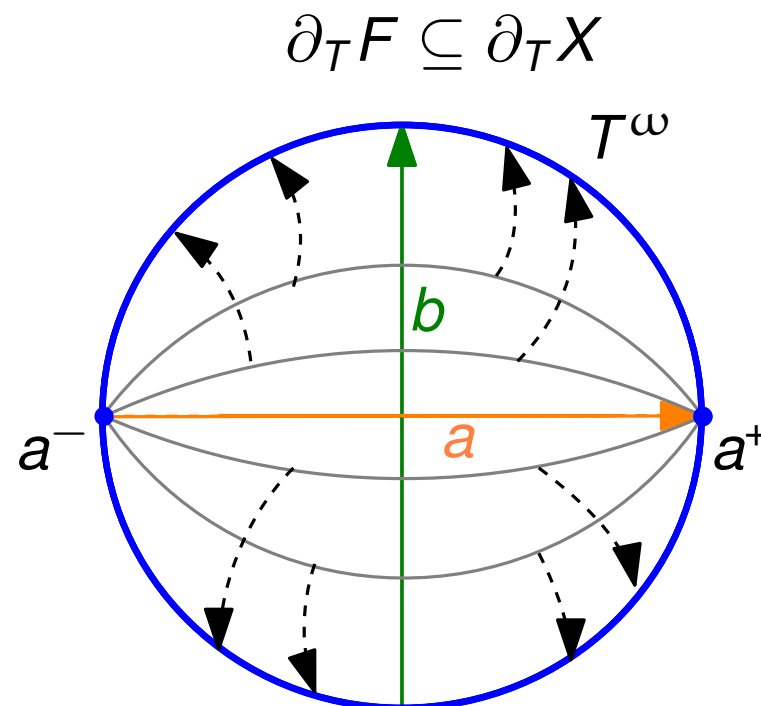
$G \curvearrowright X$ CAT(0)

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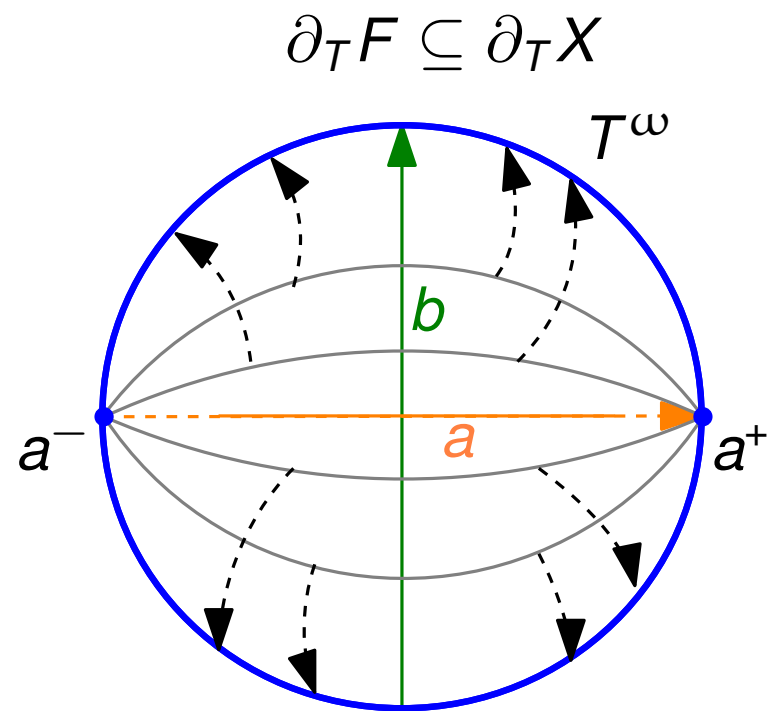
$F \subseteq X$ flat
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$\Rightarrow \partial_T F$ is an attracting top-dimensional sphere!

Now, apply a splitting criterion of Ricks (2020)!

Thank you for your attention!



Proof sketch of Claim 1

Strategy: Use Dynamics on Tits boundaries (Guralnik, Swenson, Ricks)

Definition (Tits boundary): Let X CAT(0).

$\partial_T(X) := (\partial X, d_T)$ is the *Tits boundary* of X .

|
Tits distance:

Tits distance:

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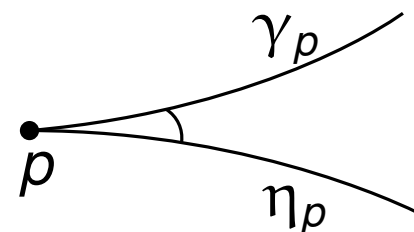
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Tits distance:

Tits distance: Let $p \in X$.

$\angle_p : \partial X \times \partial X \rightarrow [0, \pi]$

$\angle_p(\bar{\gamma}, \bar{\eta}) :=$ angle between representatives at p



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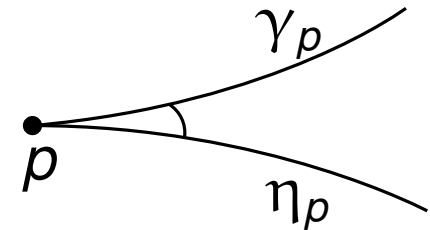
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$\angle_p(\bar{\gamma}, \bar{\eta}) :=$ angle between representatives at p

$\angle(\bar{\gamma}_1, \bar{\gamma}_2) = \sup_{x \in X} \angle_x(\bar{\gamma}, \bar{\eta})$



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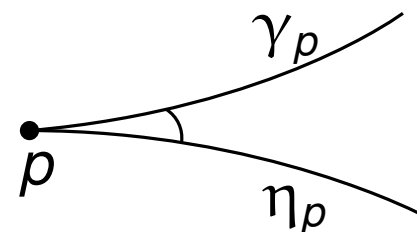
|
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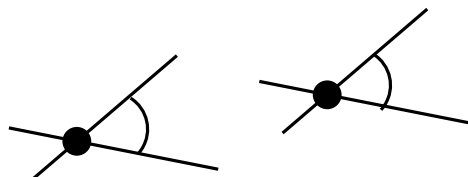
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\mathbb{R}^2



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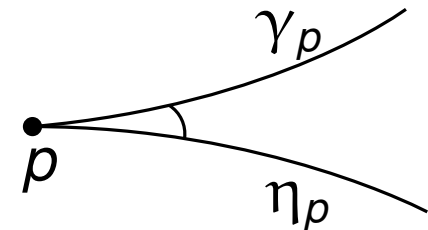
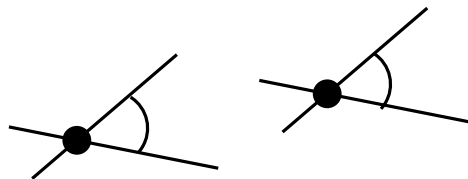
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$d_T =$ length metric induced by \angle

\mathbb{R}^2



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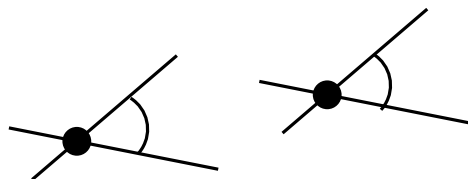
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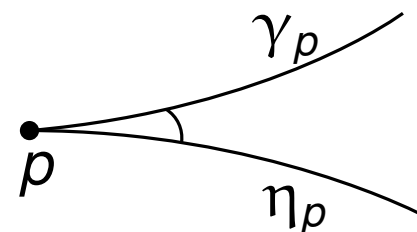
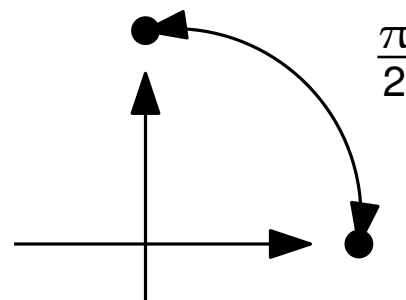
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\mathbb{R}^2



$$\partial_T \mathbb{R}^2 = S^1$$



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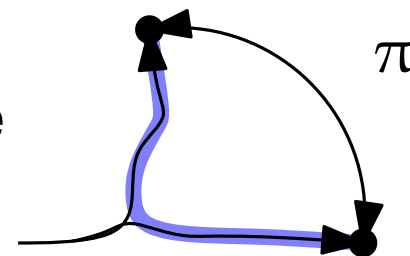
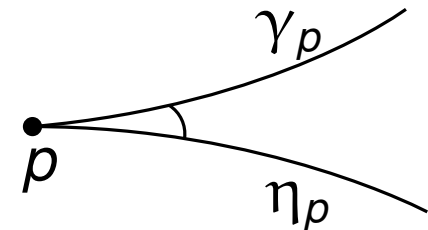
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

$d_T =$ length metric induced by \angle

$\partial_T(\text{tree}) =$ discrete space






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Strategy: Use Dynamics on Tits boundaries (Guralnik, Swenson, Ricks)

space X	∂X	$\partial_T X$
■ \mathbb{R}^2		
■ tree T	\mathcal{C}	discrete

Proof sketch of Claim 1

Strategy: Use Dynamics on Tits boundaries (Guralnik, Swenson, Ricks)

space X	∂X	$\partial_T X$
■ \mathbb{R}^2		
■ \mathbb{H}^2		discrete
■ tree T	\mathcal{C}	discrete